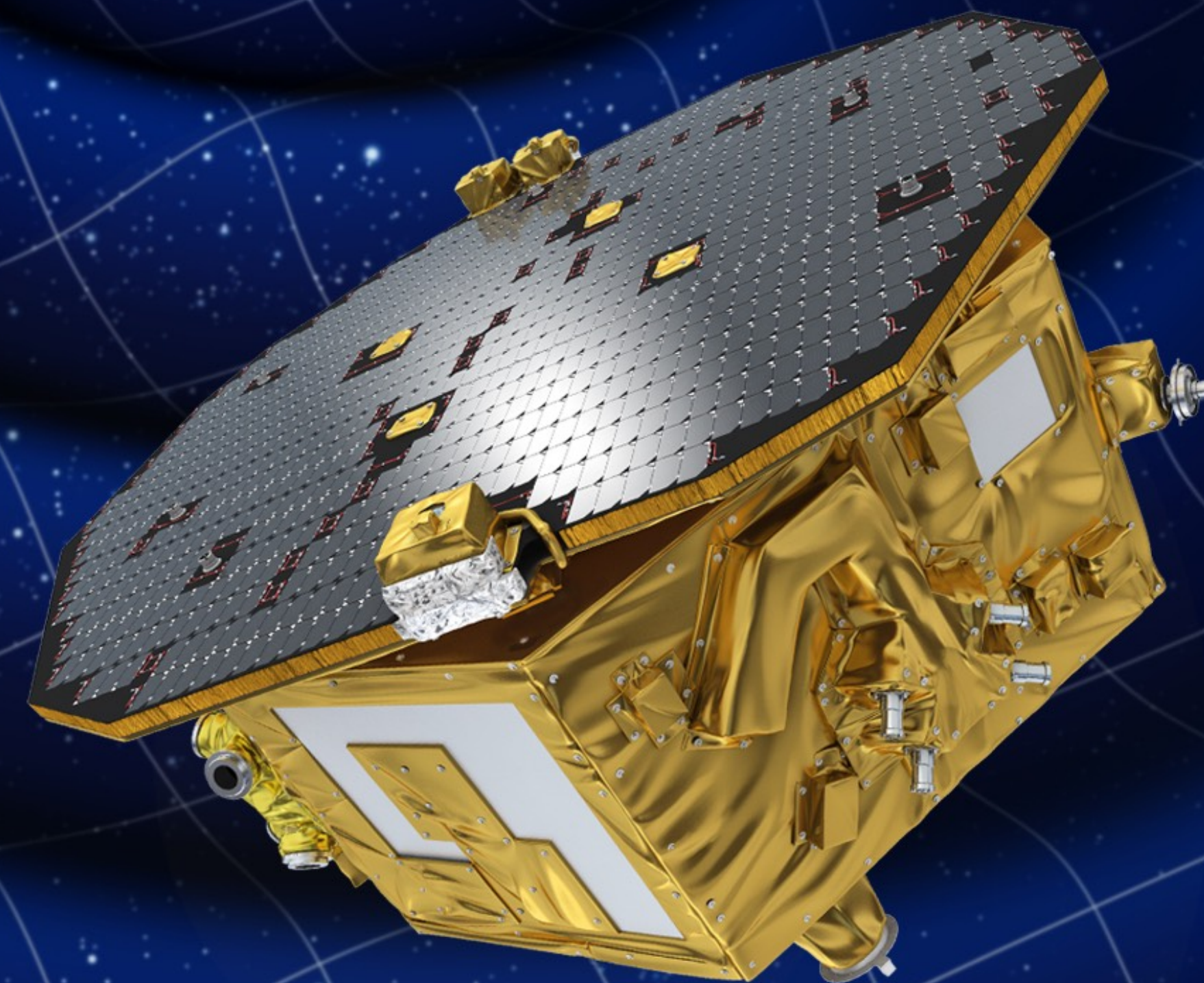


# **lisa pathfinder**

**FIRST STEPS TO OBSERVING  
GRAVITATIONAL WAVES FROM SPACE**

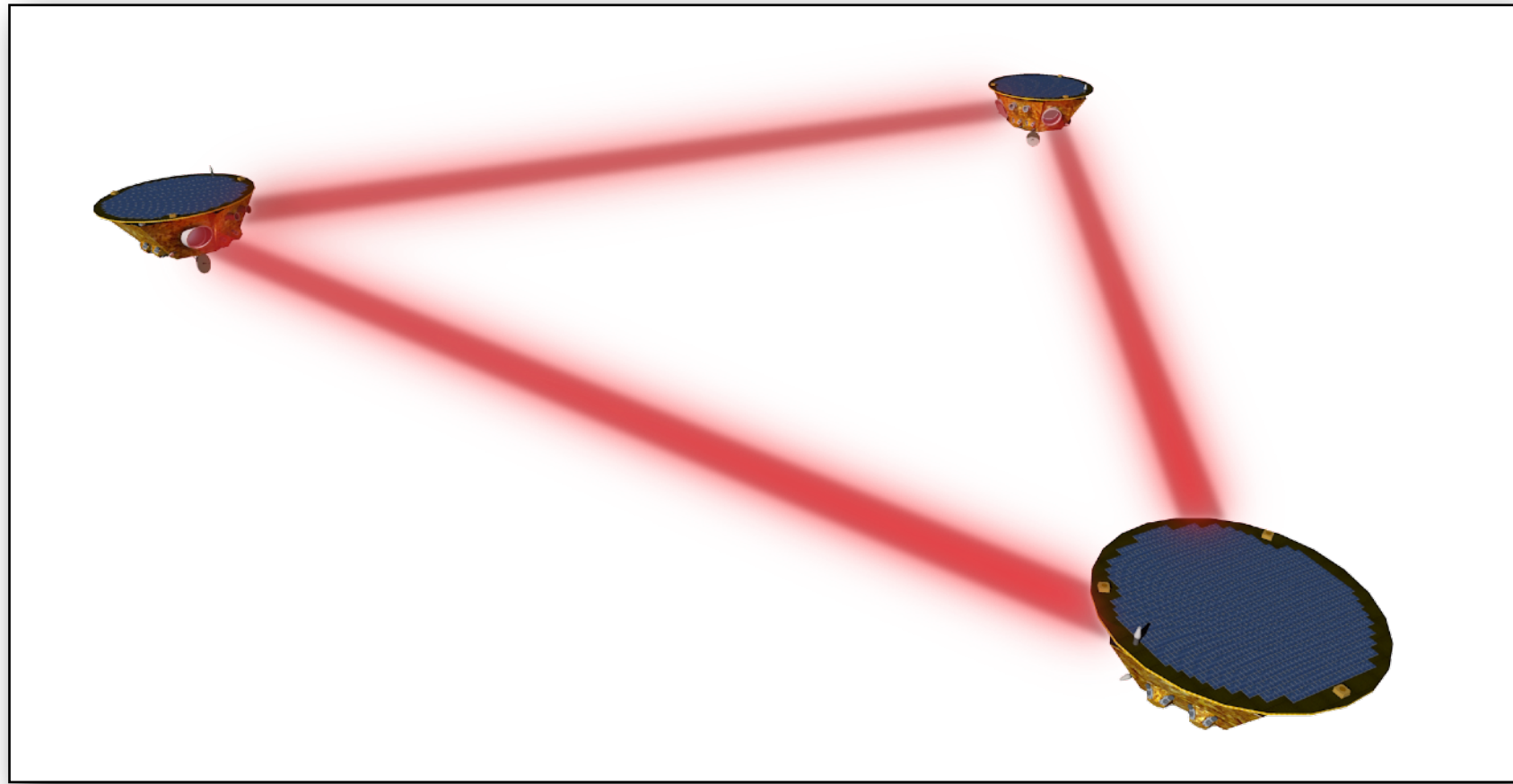
## **LISA Pathfinder and the route to LISA**

**Paul McNamara**  
ACES workshop  
Paris, October 2019



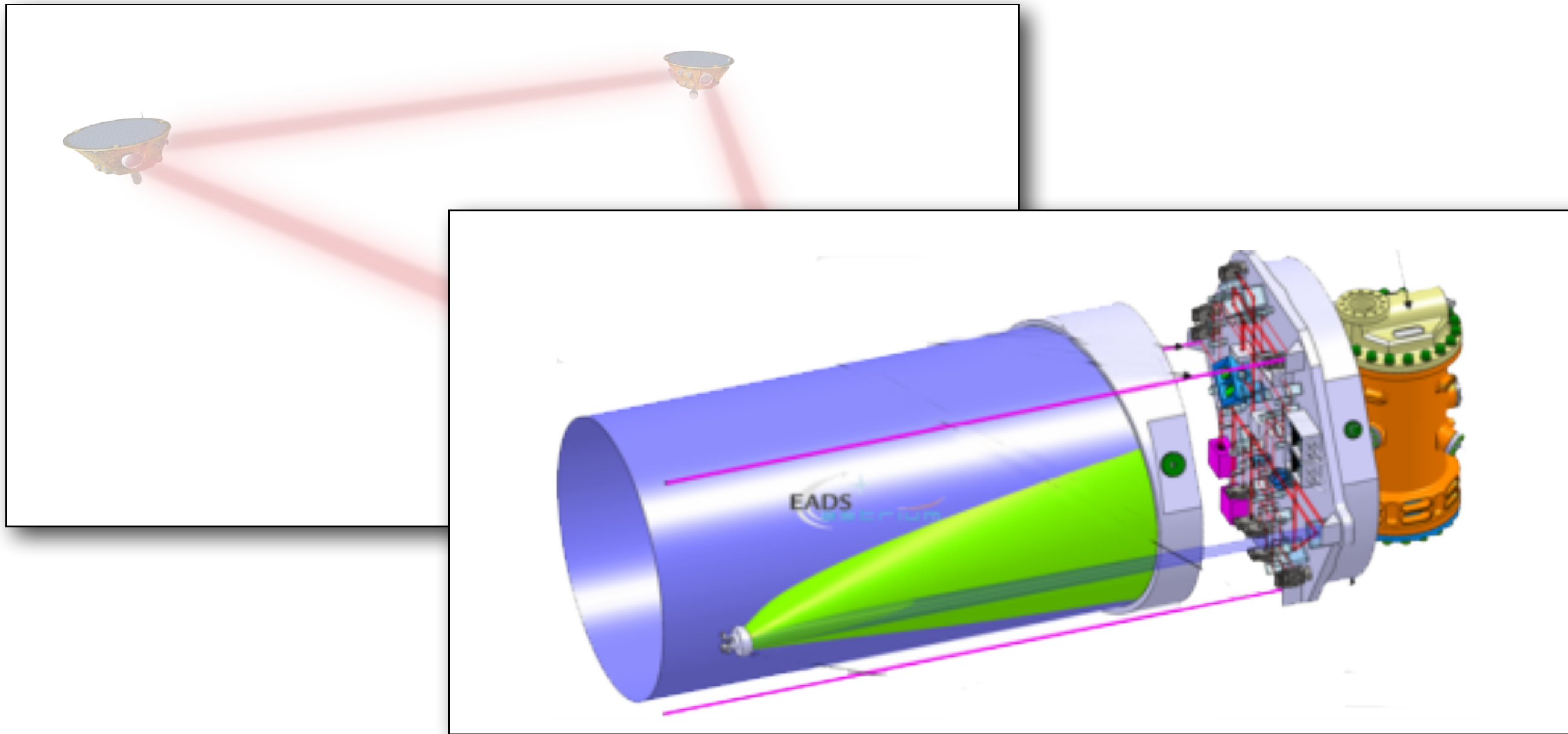
- LISA Pathfinder (LPF) is the first step in the observation of gravitational waves from space
- LPF launched on a VEGA launcher from Kourou on 3 December 2015
- Goal of mission: demonstrate free-fall within one order of magnitude of that required by LISA
  - ***Performance surpassed even our most optimistic expectations!***
- LPF essentially shrinks one arm of LISA from ~million km down to ~40cm
  - Gives up the sensitivity to gravitational waves
  - Maintains (and worsens) the instrument noise which could dominate the GW signal





## LISA:

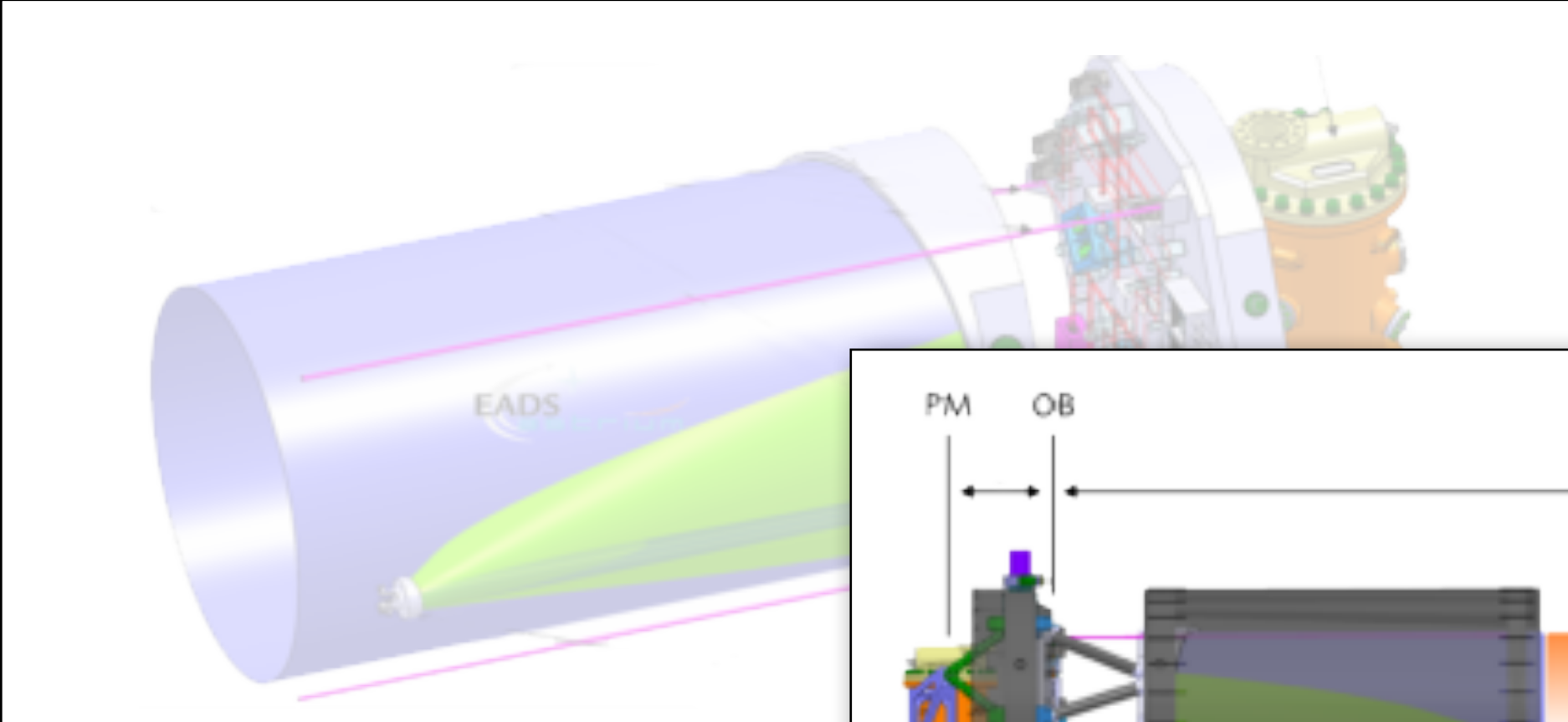
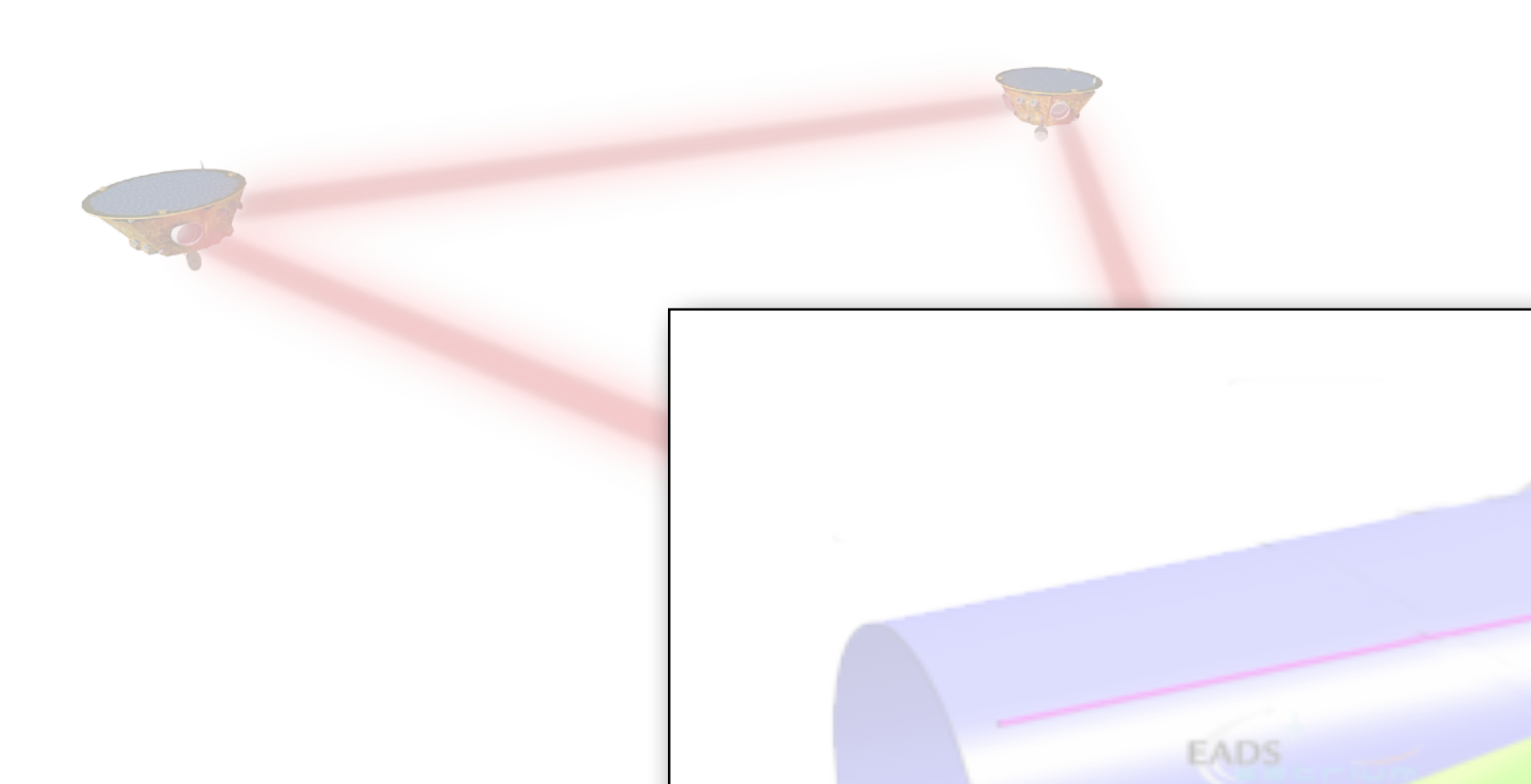
- 3 spacecraft, separated by ~million km
- Role of each spacecraft is to protect the fiducial test masses from external forces



## LISA:

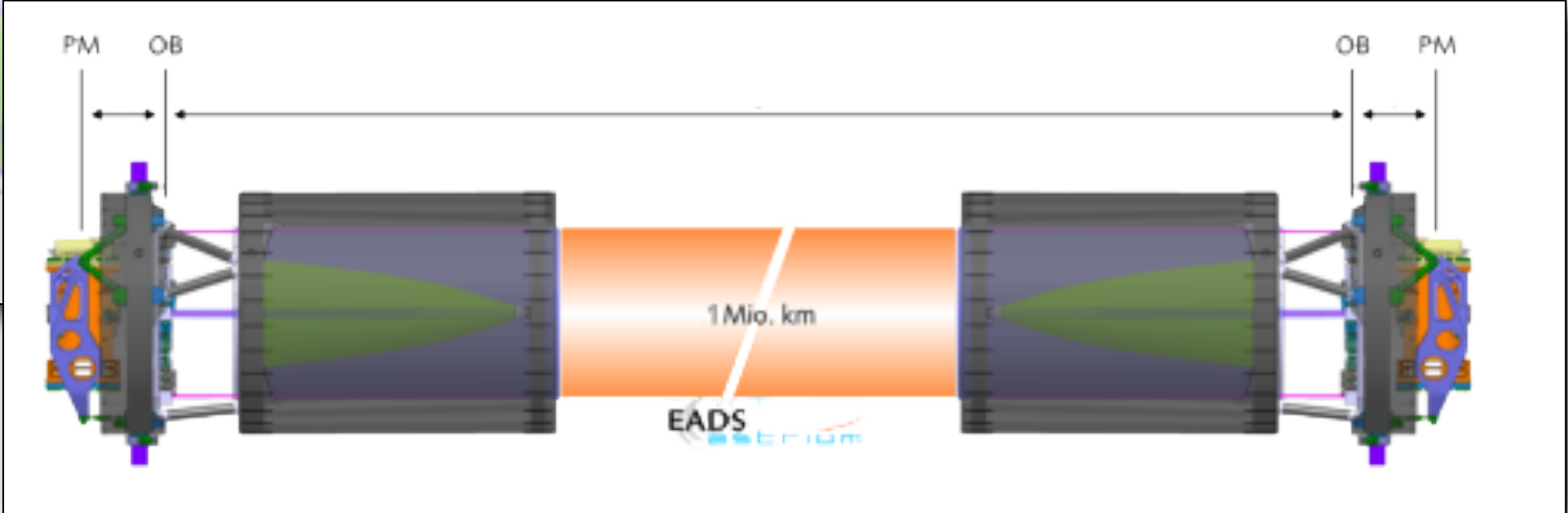
- Locally measure distance from TM to s/c using:
  - Laser interferometry along sensitive axis (between s/c)
  - Capacitive sensing on orthogonal axes
- TM displacement measurements are used as input to DFACS which controls position and attitude of s/c with respect to the TM

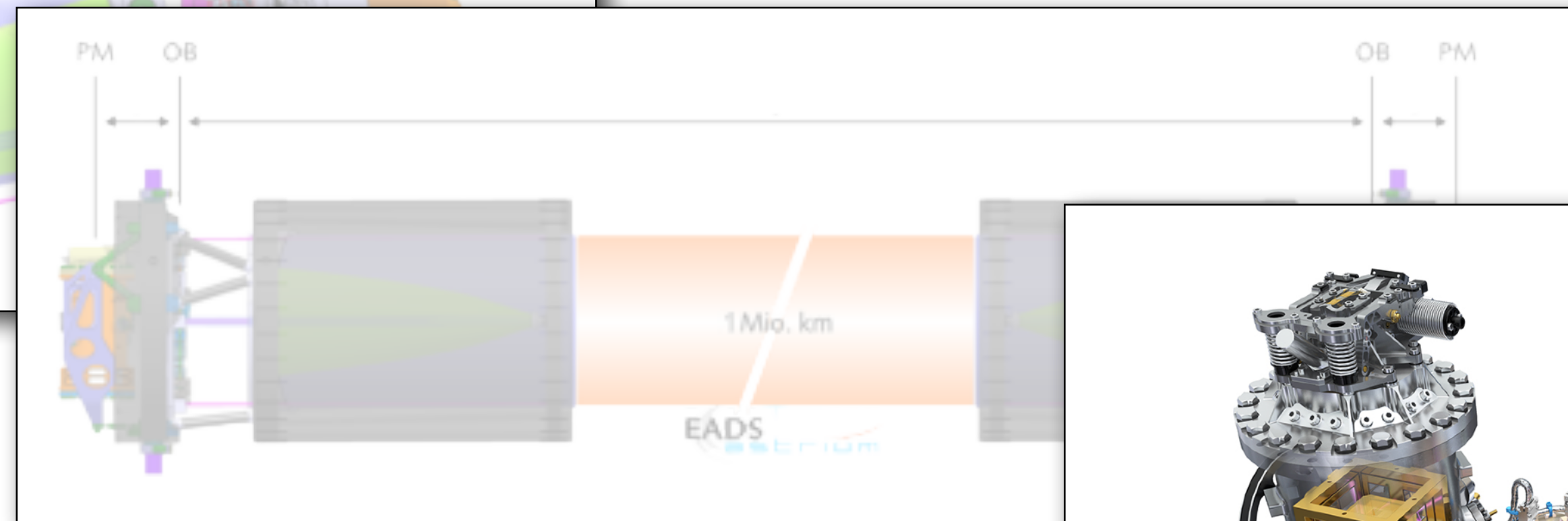
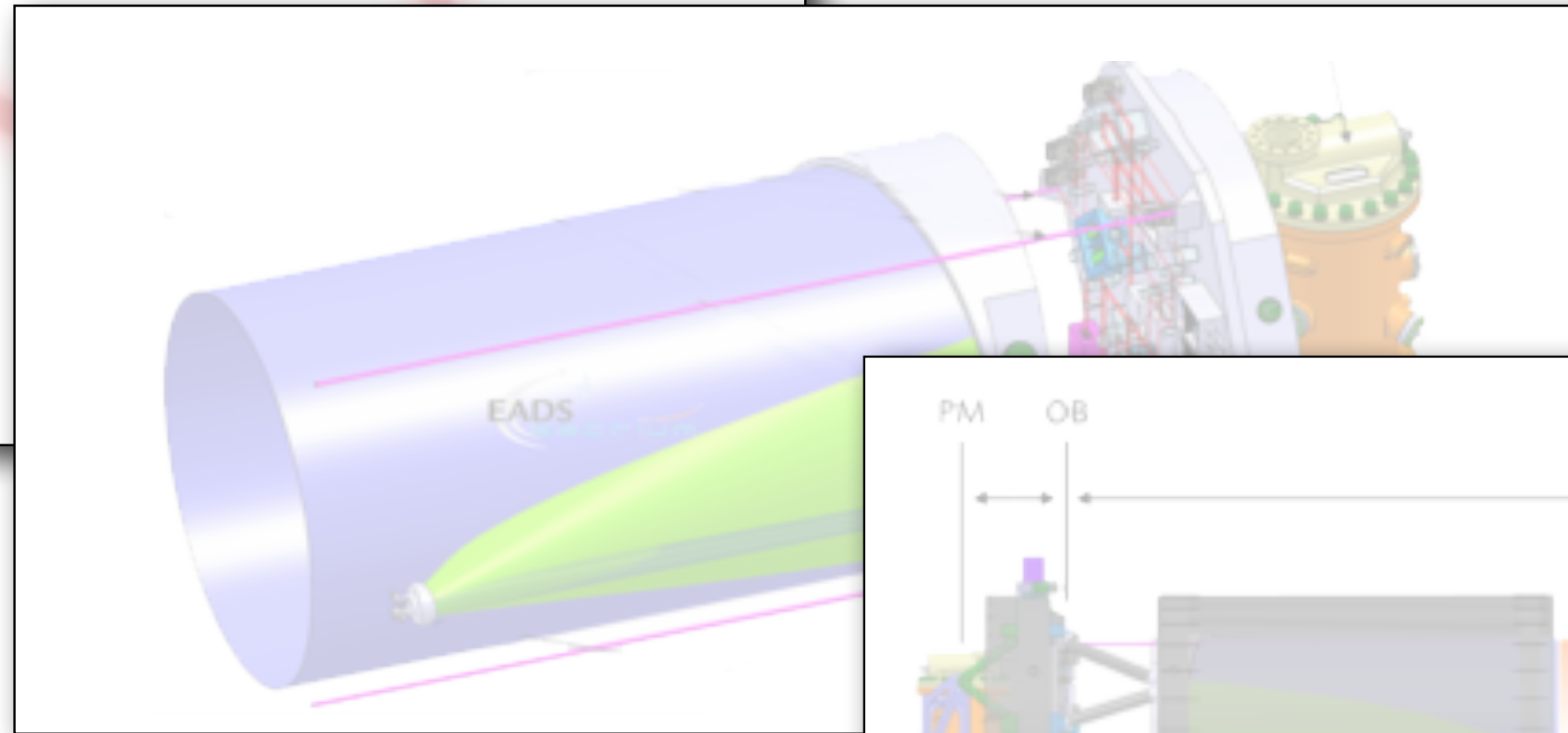
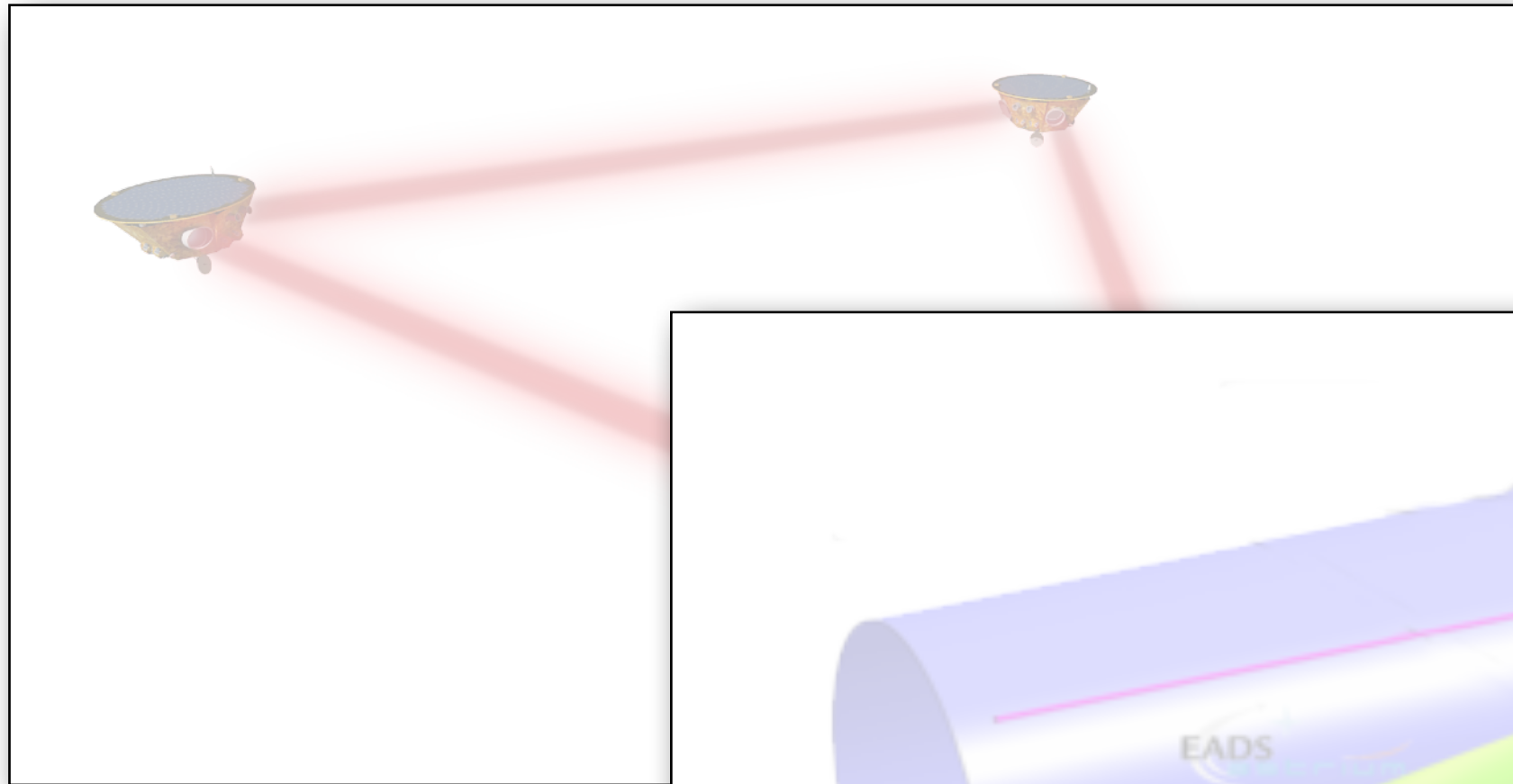
# LISA to LISA Pathfinder



**LISA:**

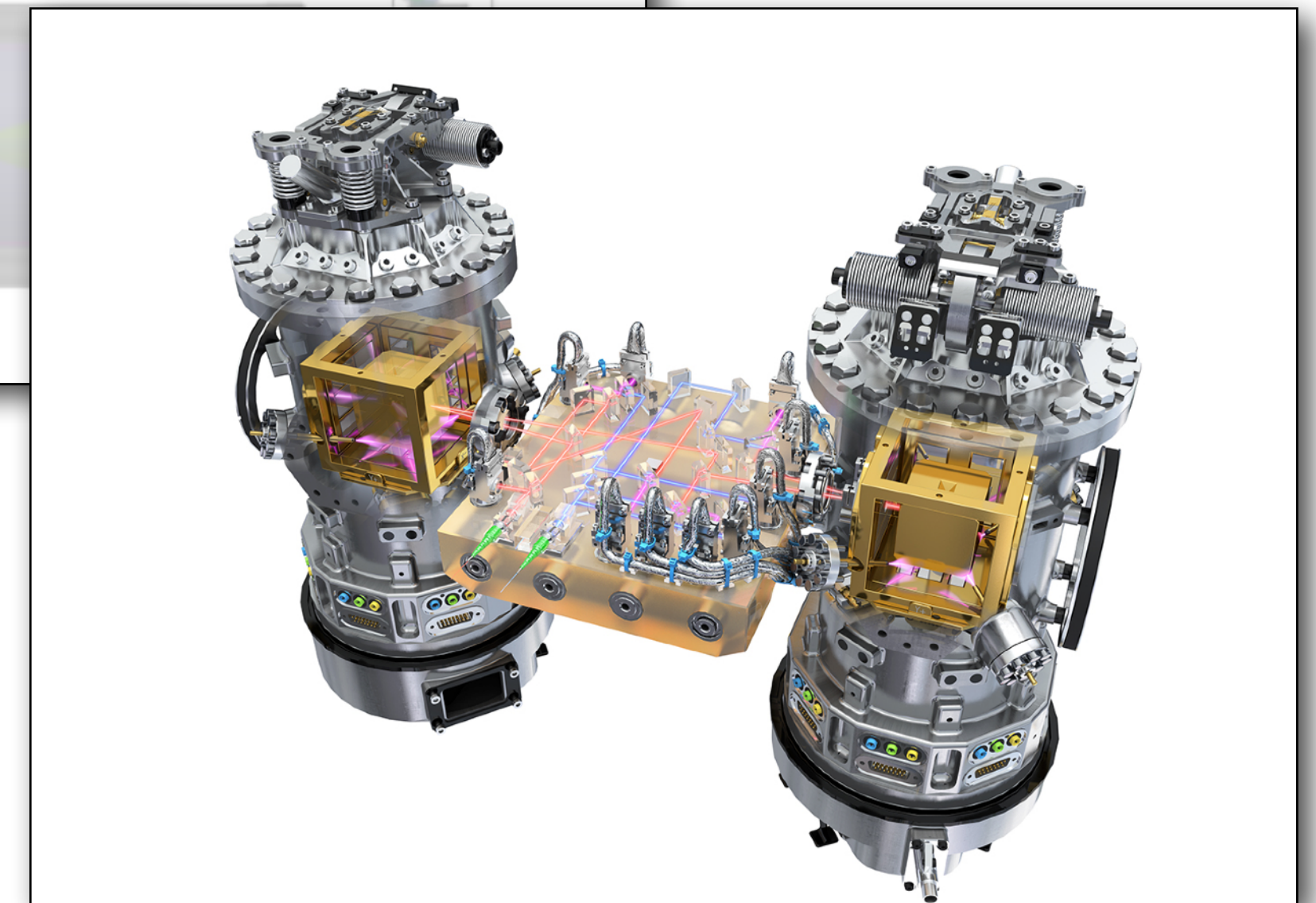
- Measure distance between s/c using laser interferometry
- Build TM-TM distance by combining:  
 $(TM_1 \rightarrow s/c) + (s/c \rightarrow s/c) + (s/c \rightarrow TM_2)$



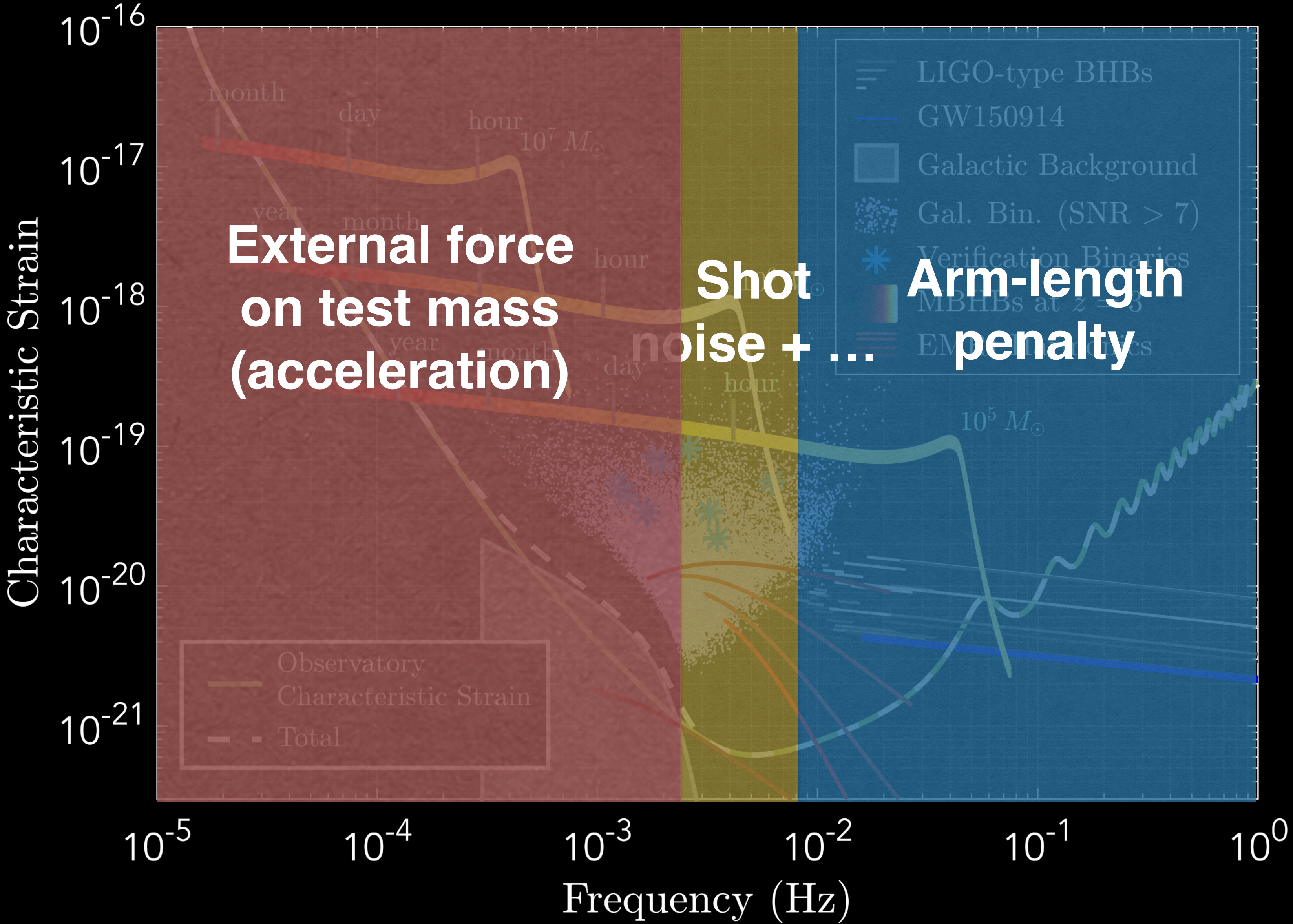


## LISA Pathfinder:

- Two test masses/two inertial sensors
- Laser interferometric readout of  $TM_1 \rightarrow s/c$  &  $TM_1 \rightarrow TM_2$
- Capacitive readout of all 6dof of test masses
- Drag-Free and Attitude Control System
- Micro-Newton Thrusters



# LPF and LISA



© LISA Pathfinder consists of:

- **Spacecraft**

- Provided by ESA
  - Industrial Prime Contractor: Airbus DS (UK)
- s/c also includes the drag free control software and micro-Newton thrusters

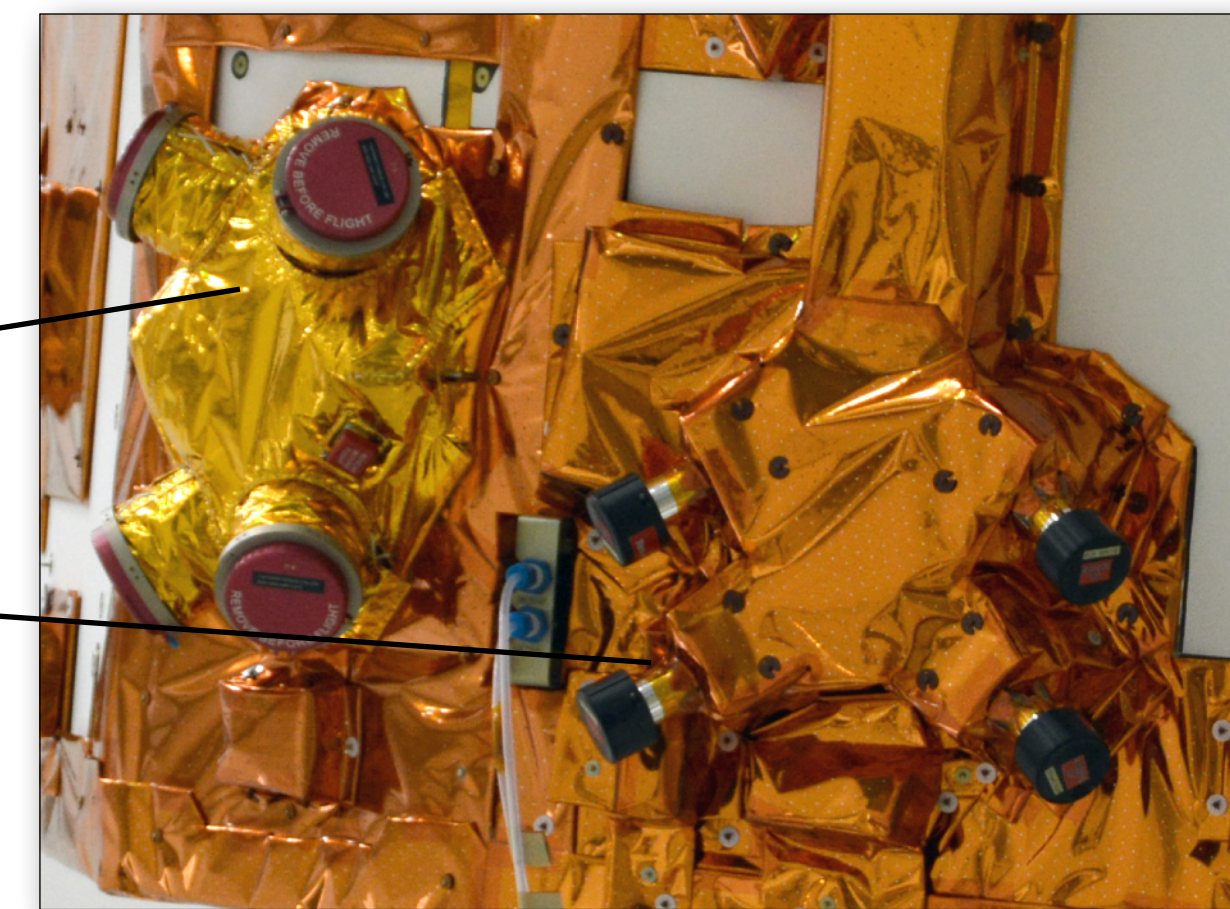
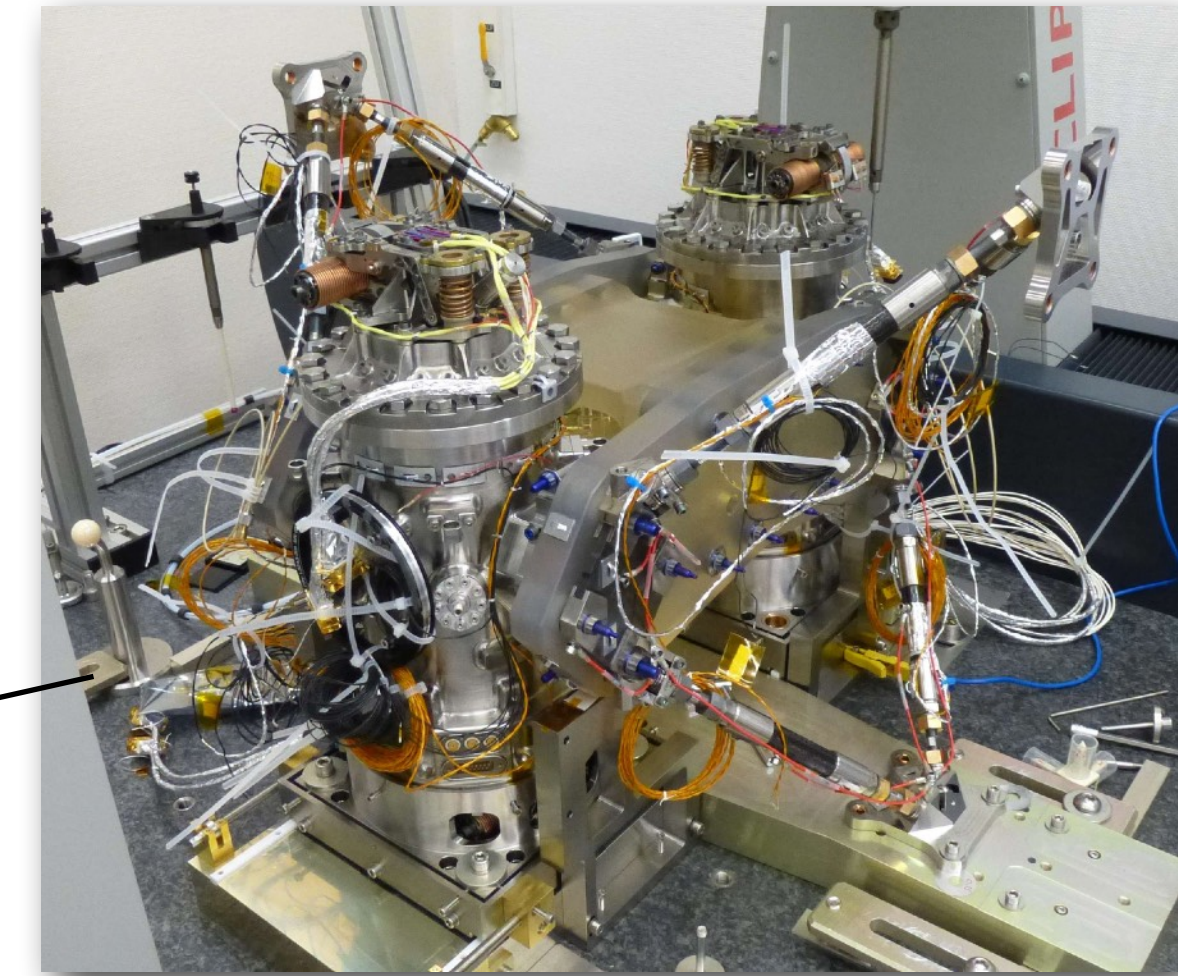
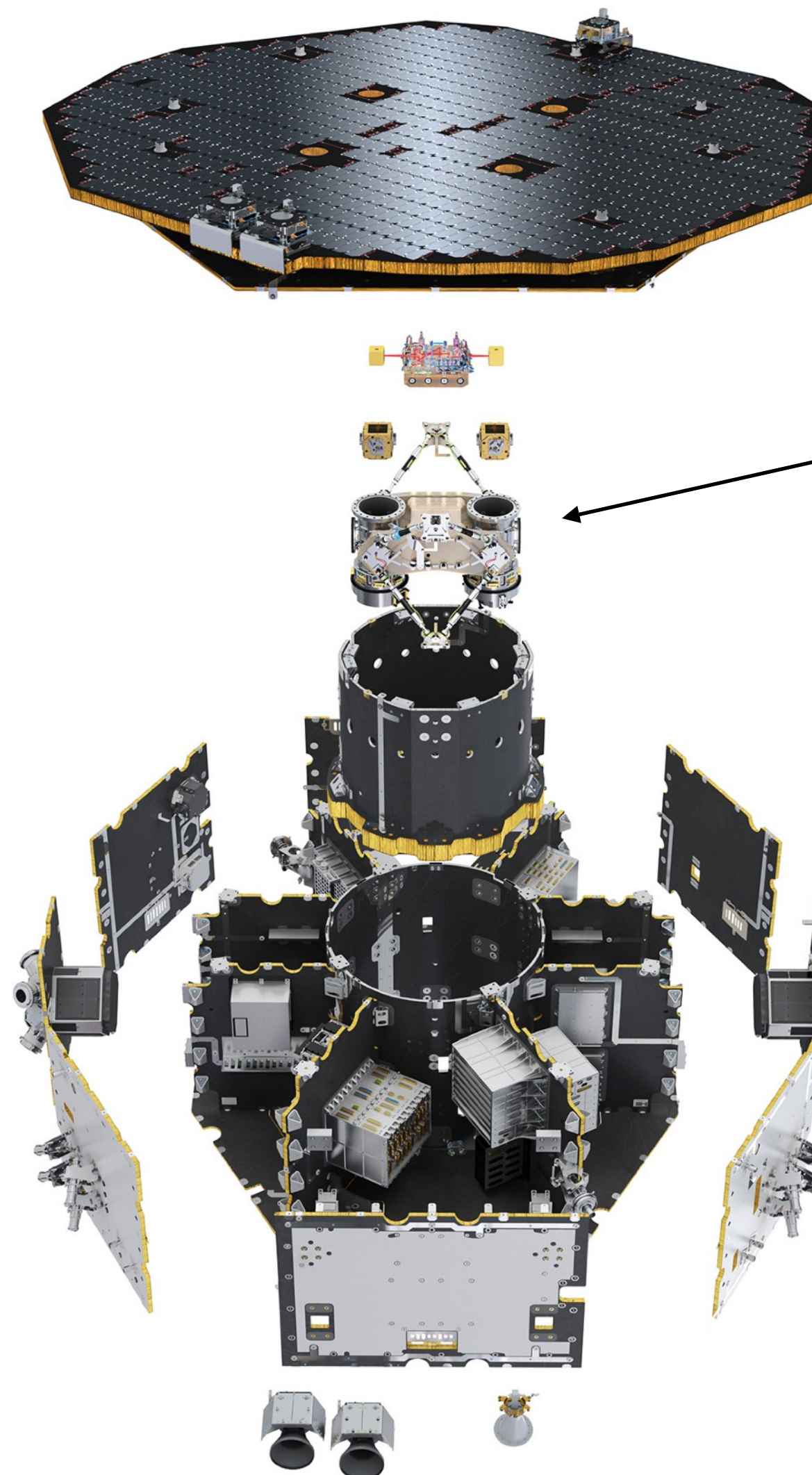
- **Payloads**

• **The LISA Technology Package (LTP)**

- Provided by European member states and ESA
- Consists of inertial sensors, interferometric readout, payload computer and diagnostic subsystem

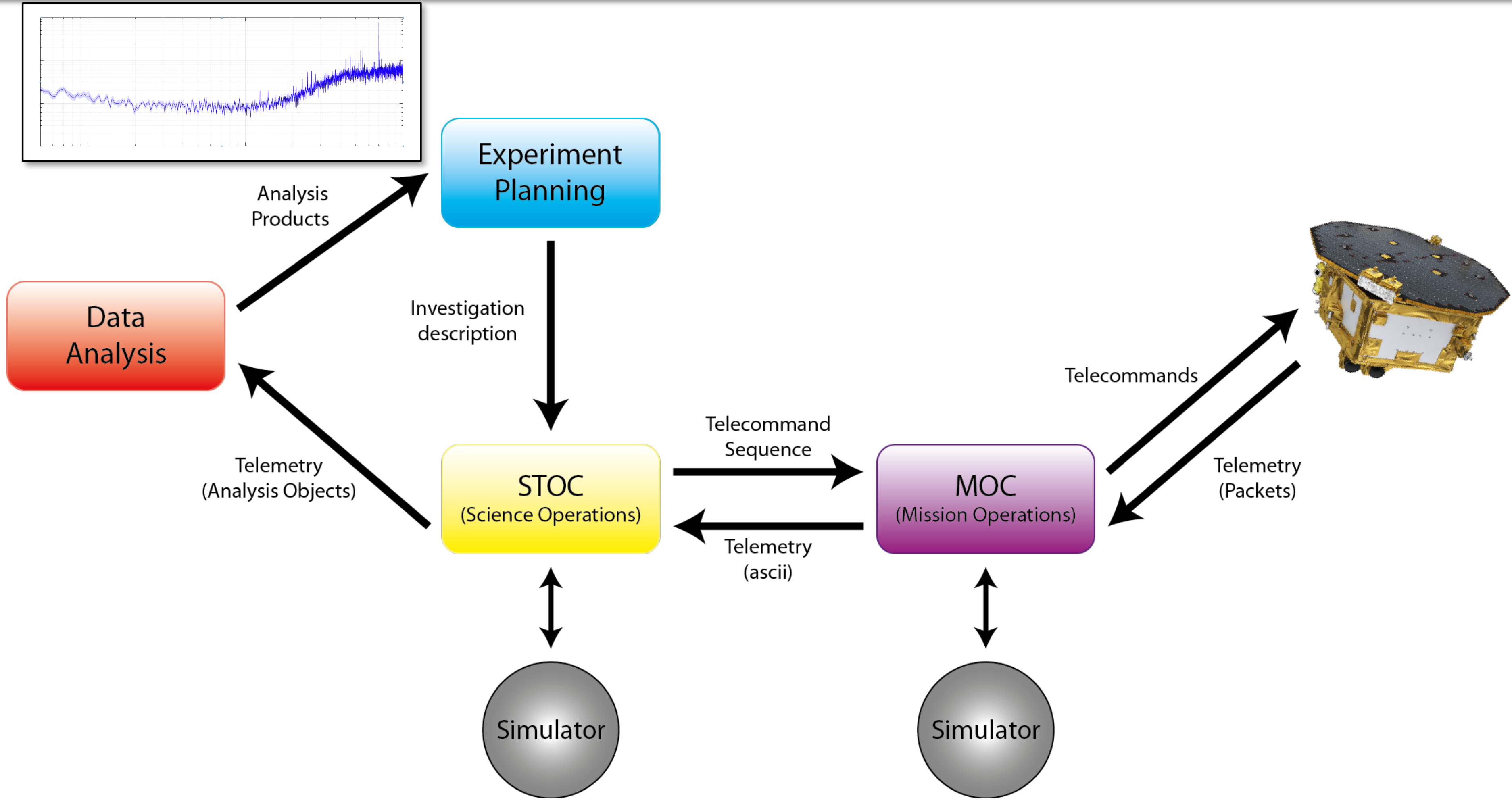
• **The Disturbance Reduction System (DRS)**

- Provided by NASA/JPL
- Consists of processor running drag-free control software and micro-Newton thrusters

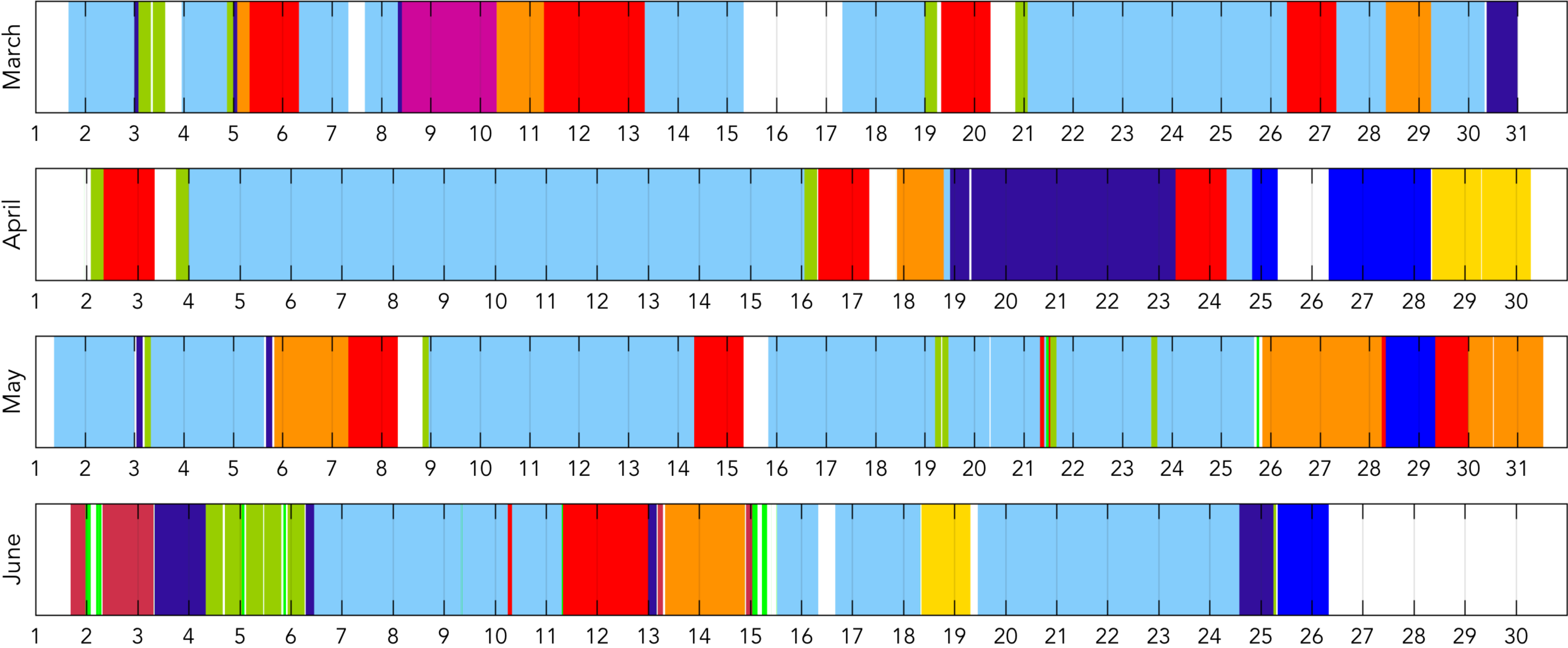




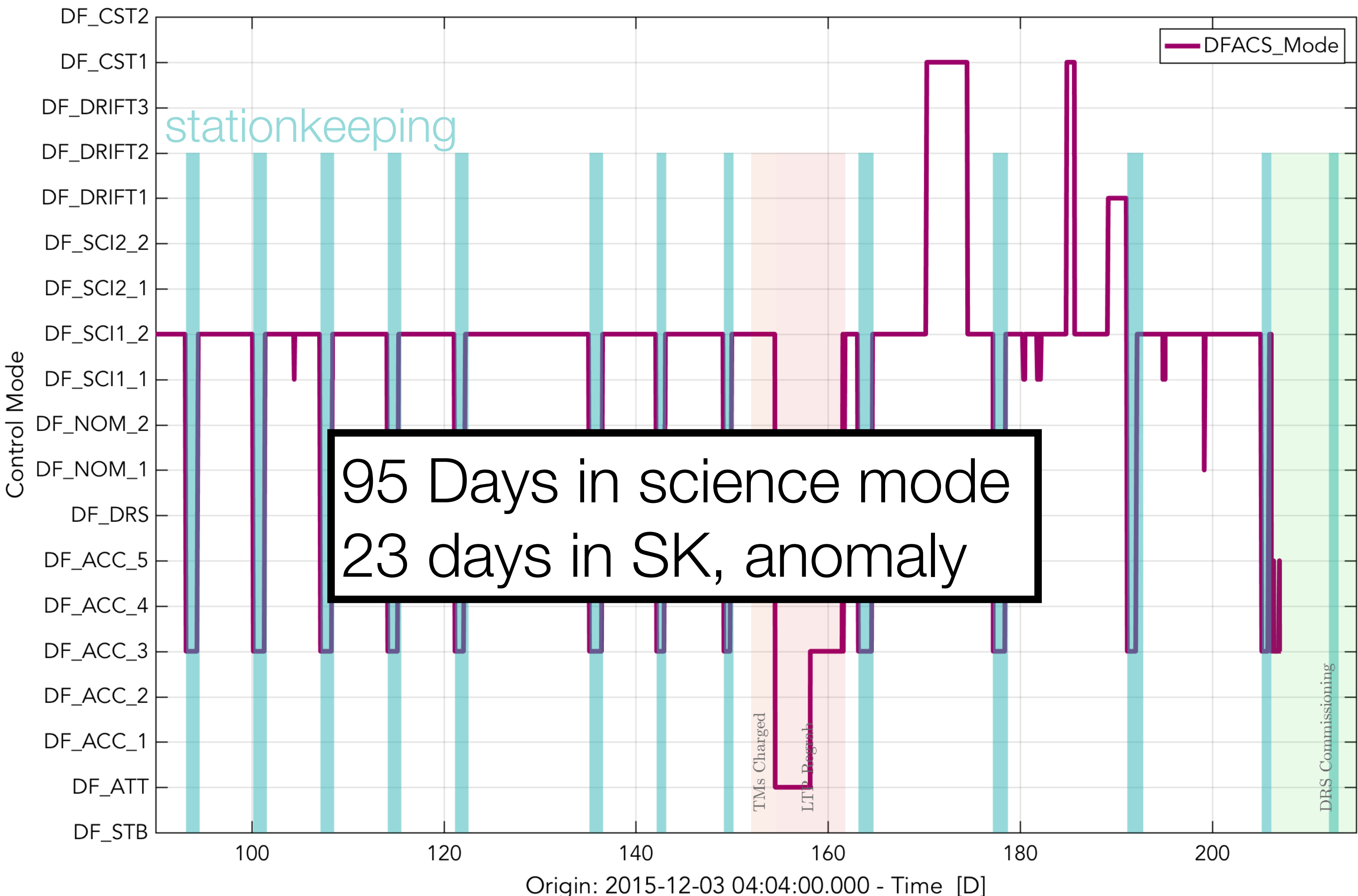
# A orbiting physics lab



# Experiments Performed



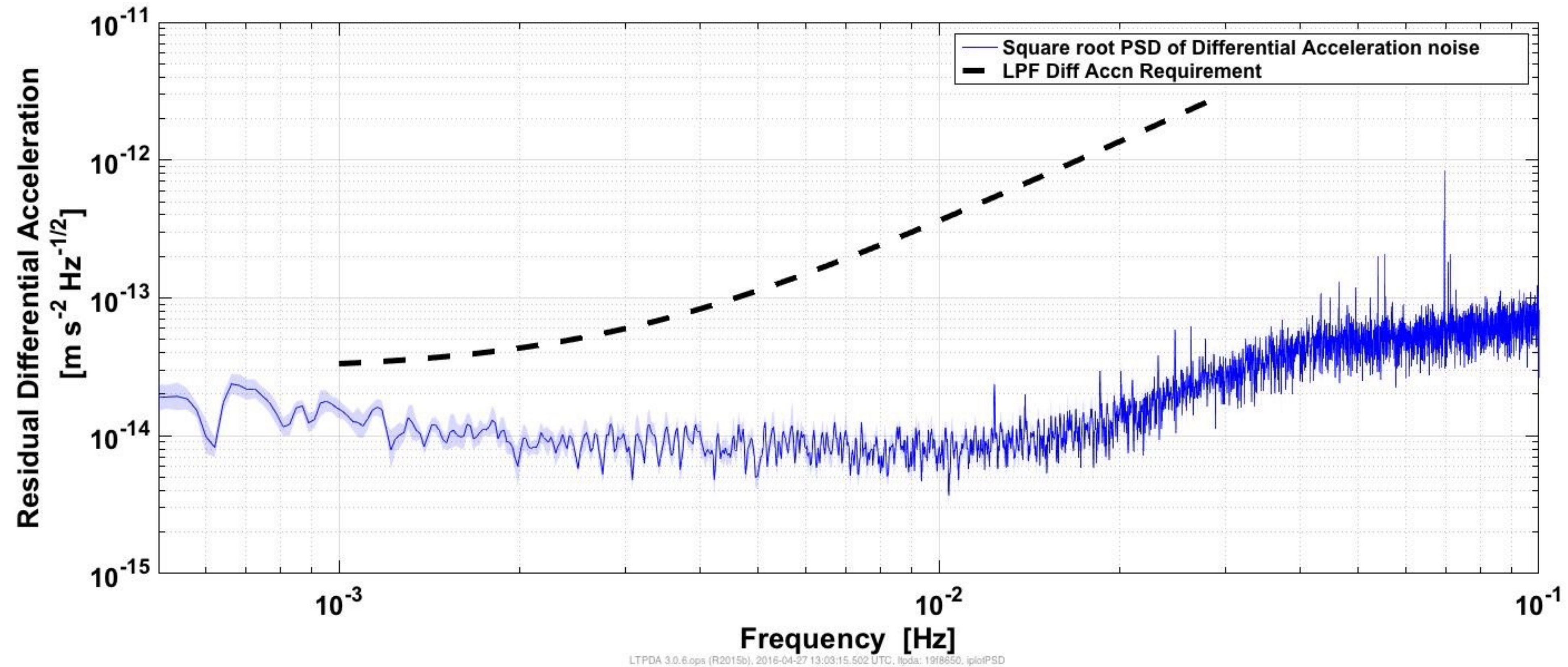
# Time in science mode



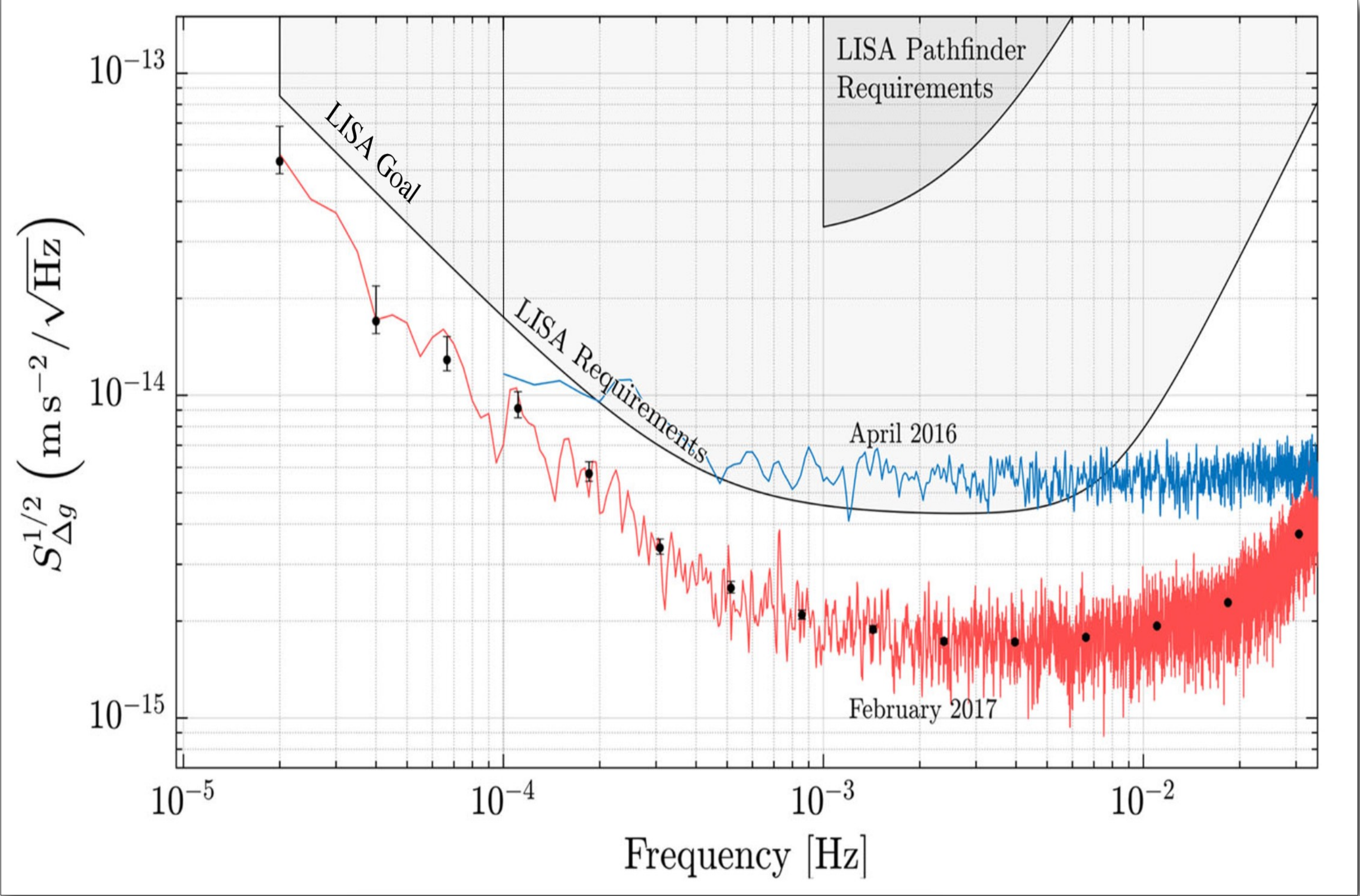
# Differential Acceleration



- © The differential acceleration between the test masses (known as “delta-g”) is the primary performance requirement of the mission...  
...and was met during commissioning!



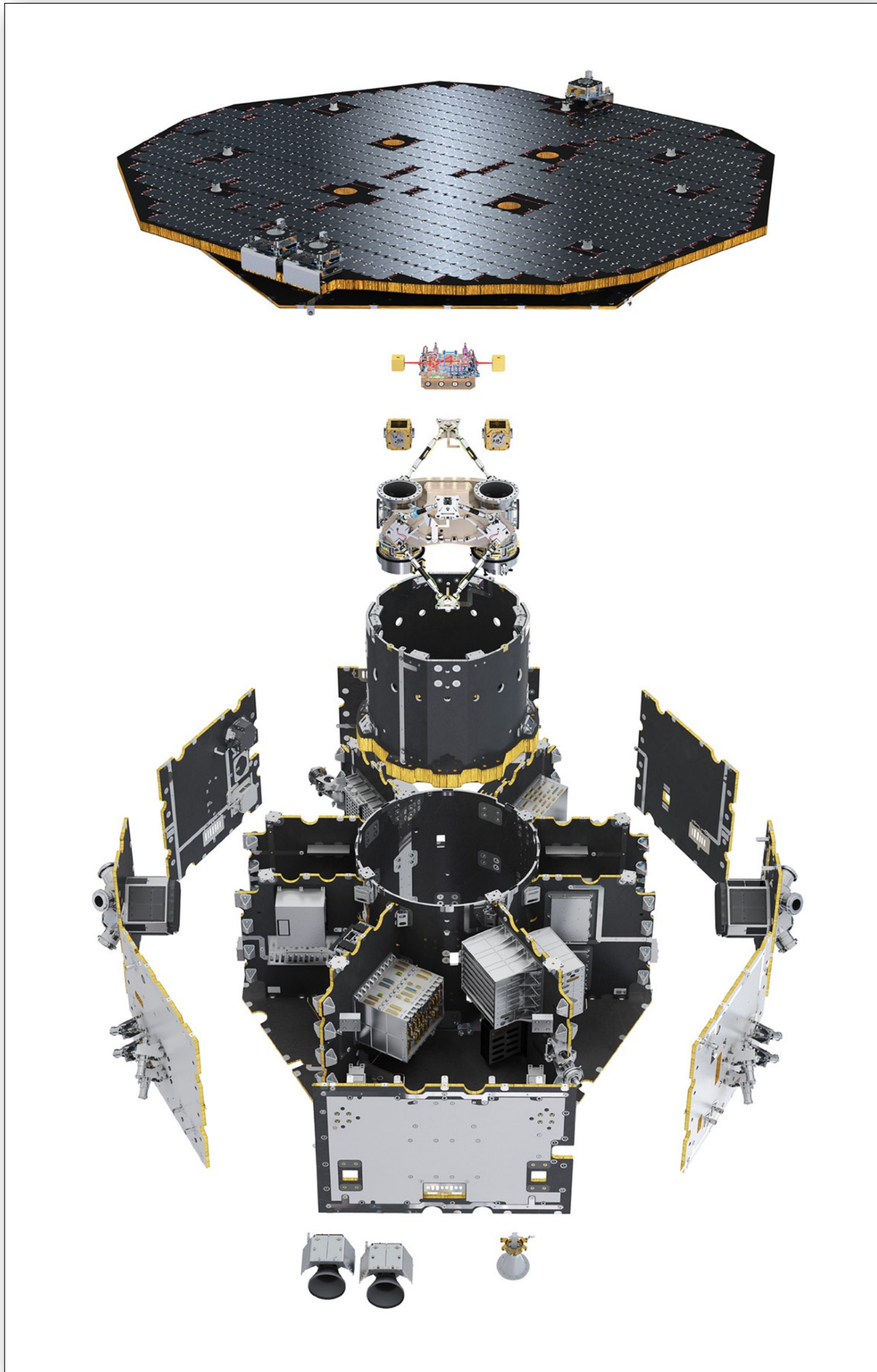
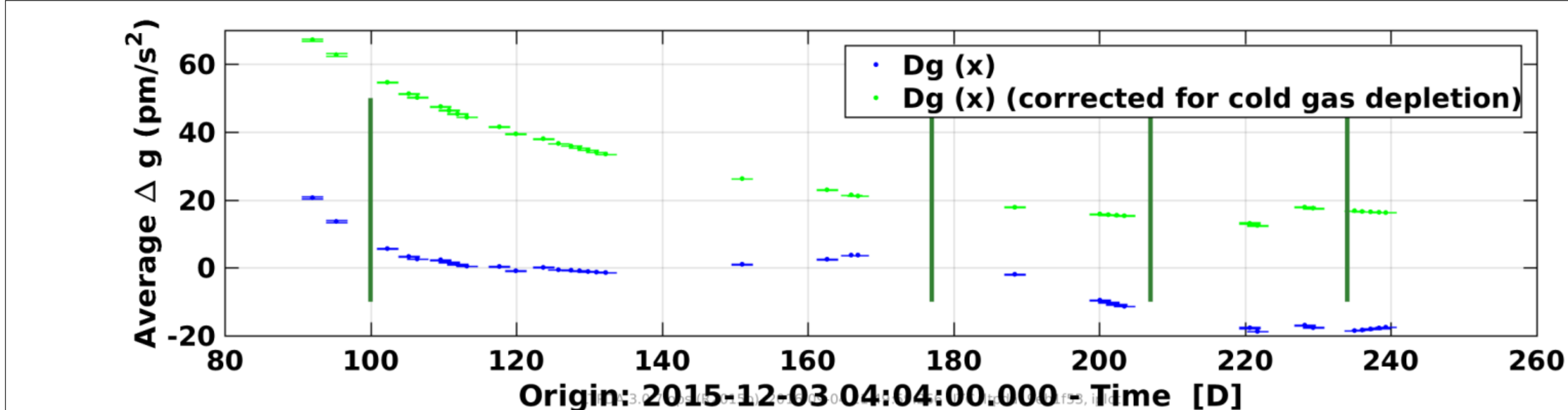
# After 1 year on orbit...



# Why so good?



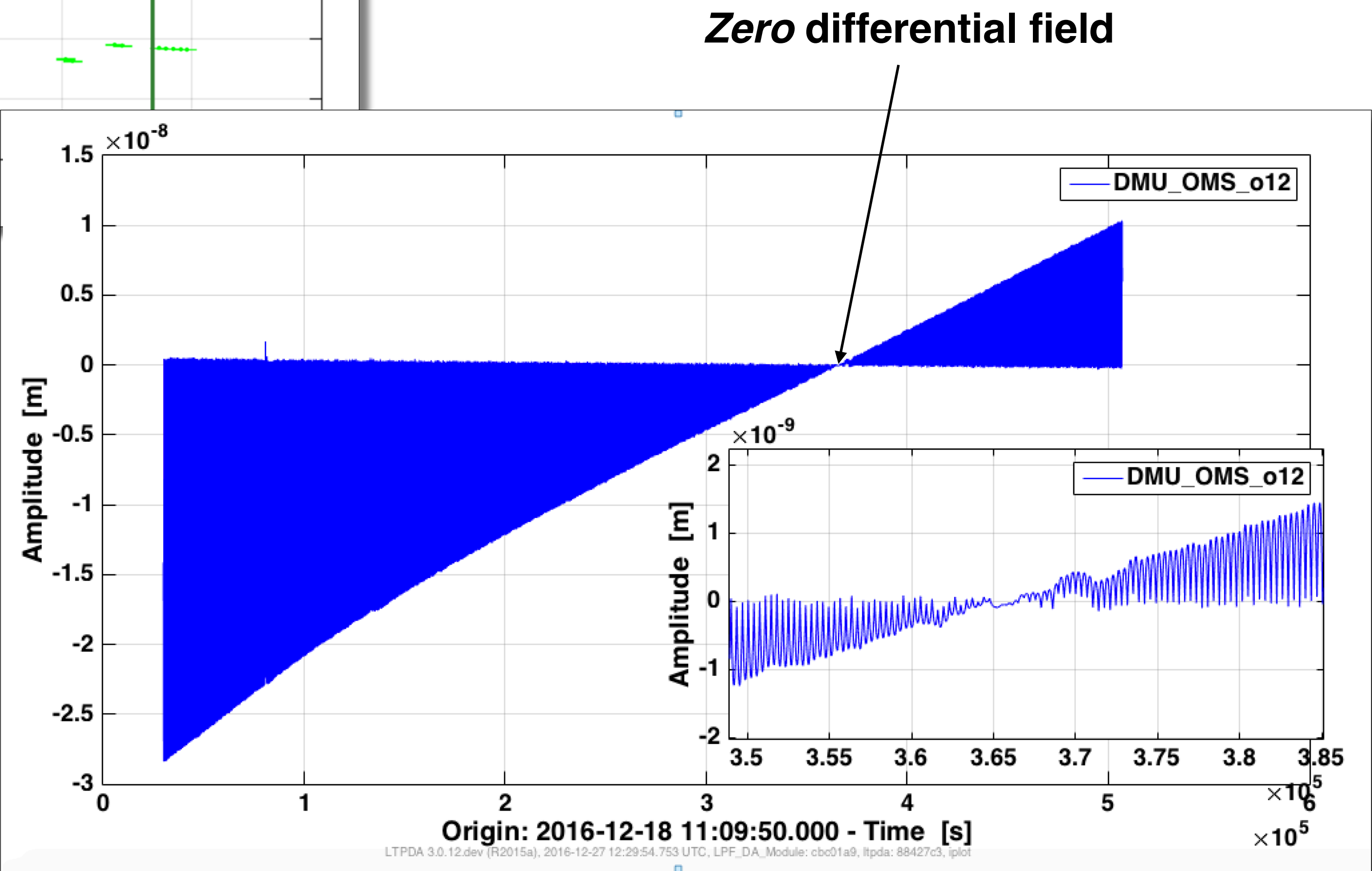
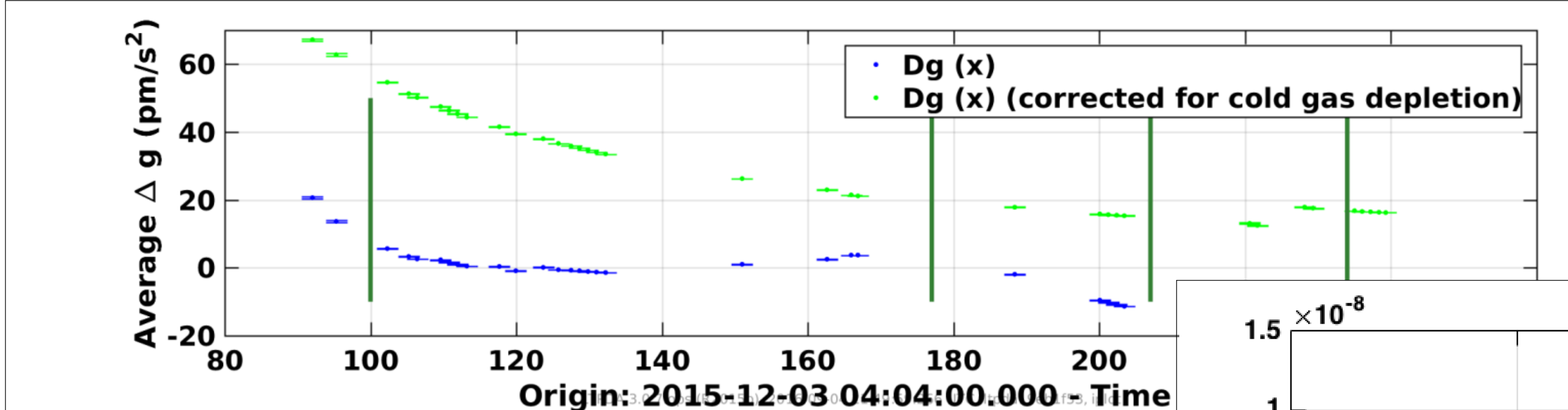
Pre-launch requirement: 1000pm/s<sup>2</sup>



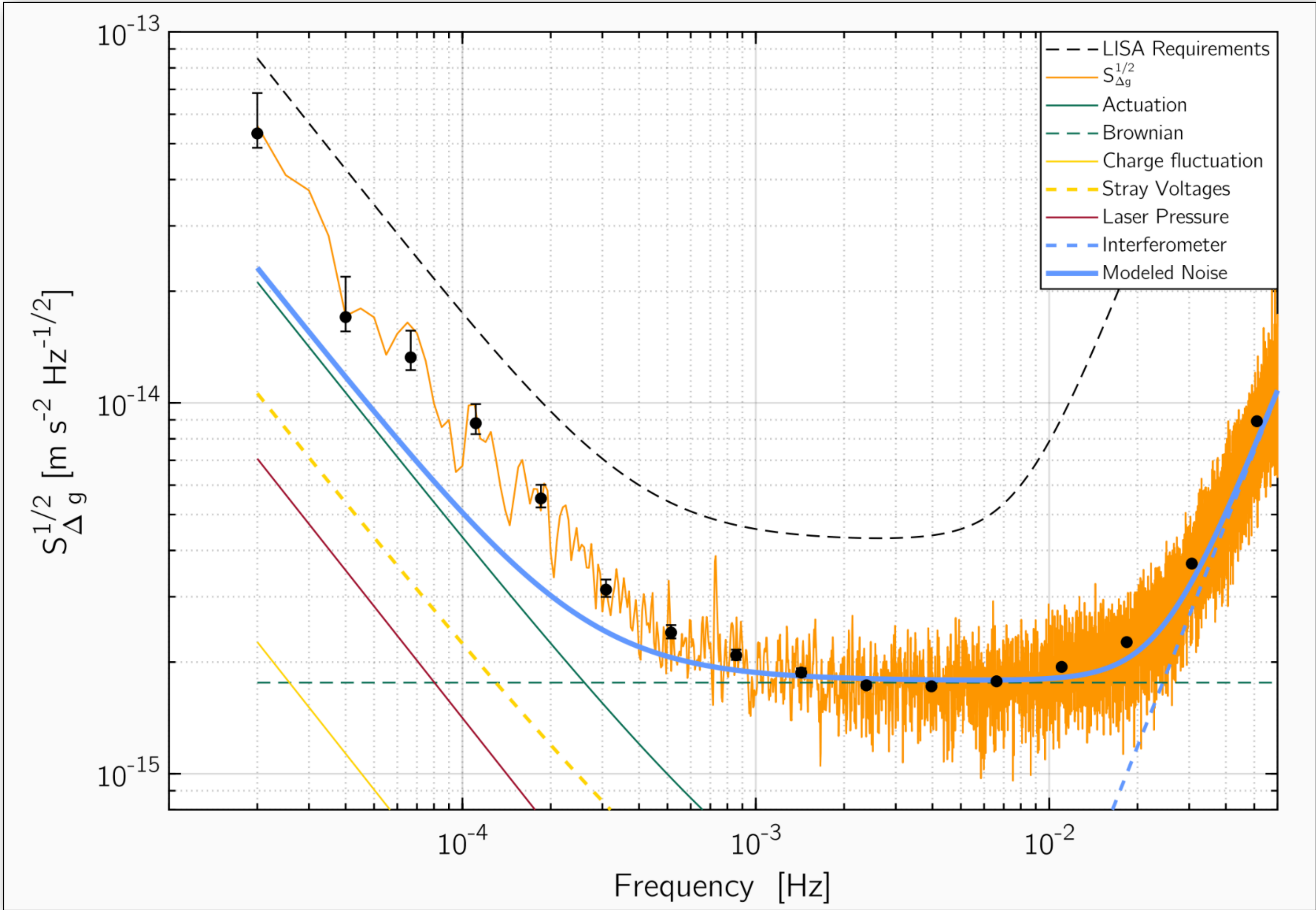
# Why so good?



Pre-launch requirement: 1000 pm/s<sup>2</sup>

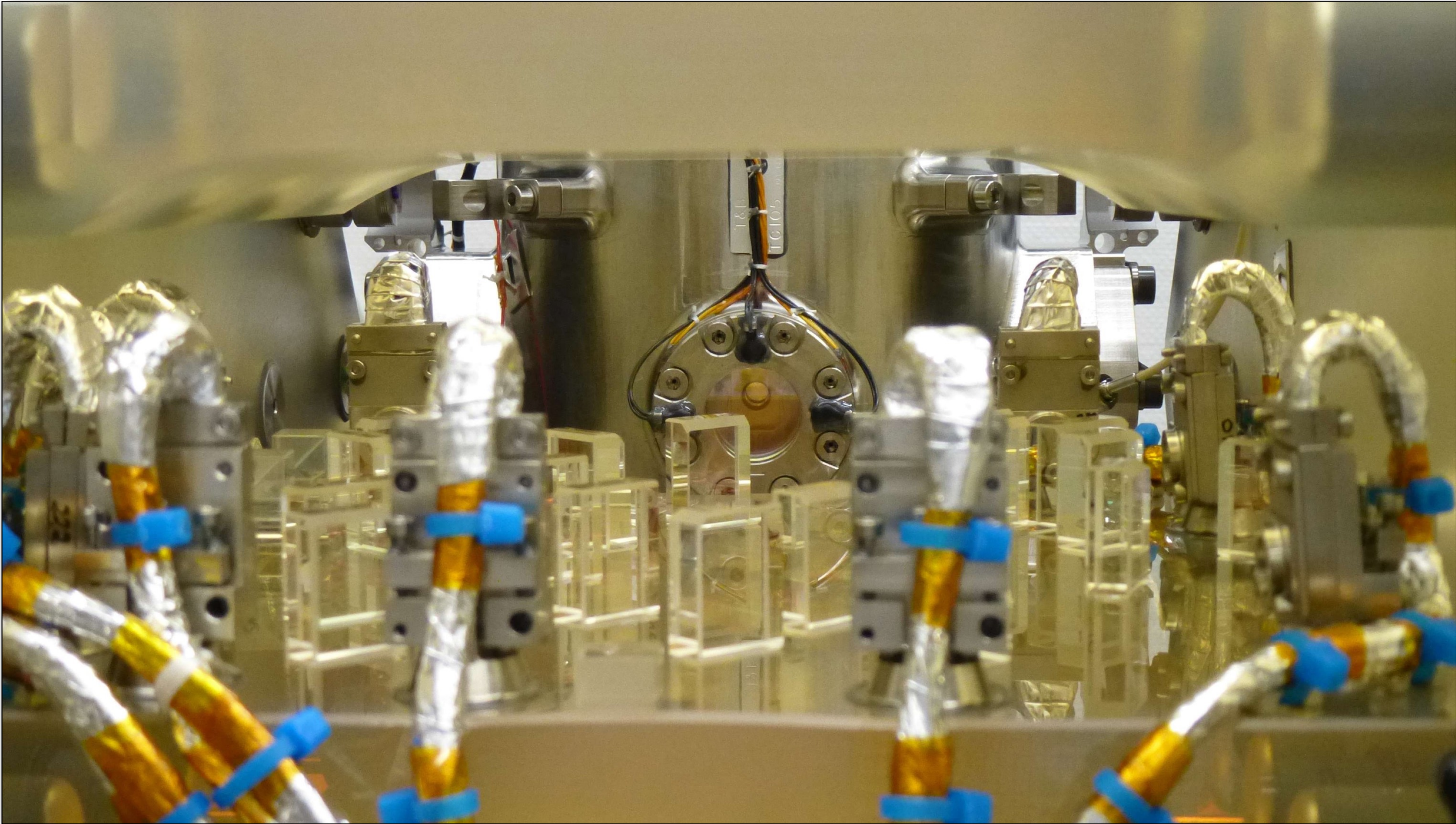


# What we understand





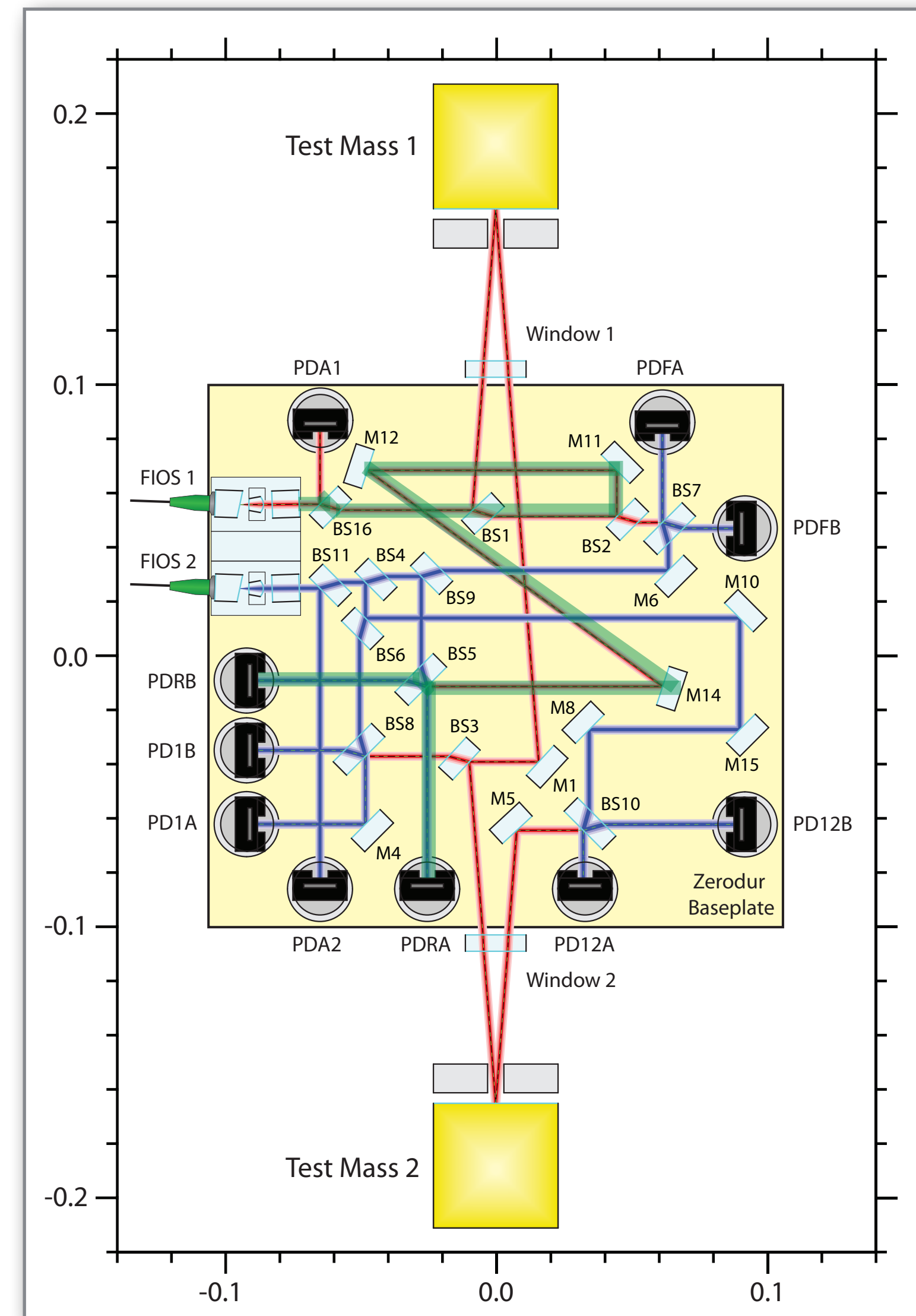
# Optical Metrology System



# Beam alignment (from ground to space)



- One major worry was OMS alignment change from ground to space
- Any distortion of the optical bench shows up as large misalignment due to lever arm of optical path on bench
- Optical bench alignment can be measured using the fixed interferometers
  - Reference ifo measurement beam is most sensitive to bench distortion



# Alignment from ground to space



Measurement Beam

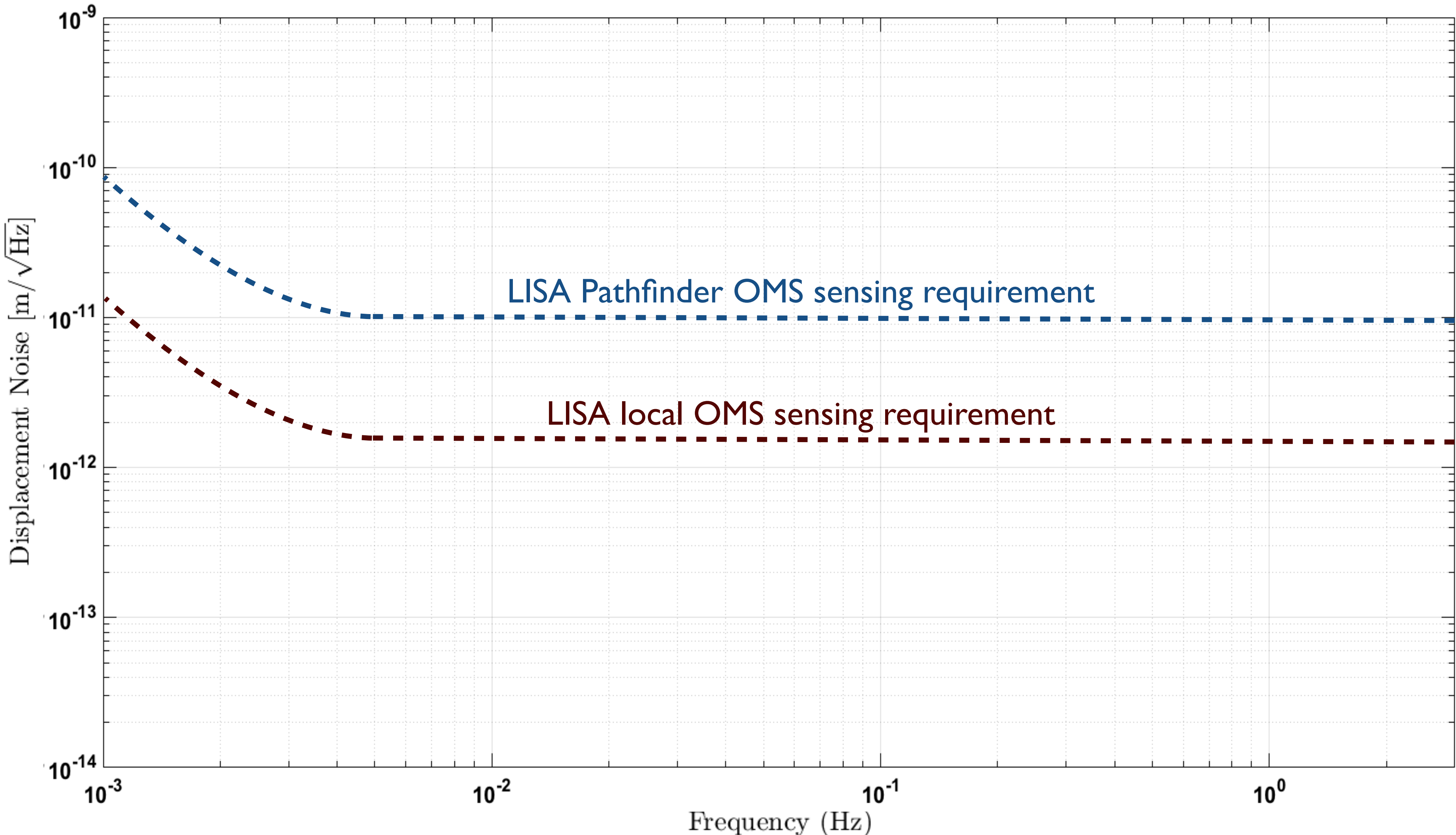
[um]			Flight	IABG	UGL	Flight - UGL	IABG - UGL	Flight - IABG
X1	A	x	34	35				-1
		y	-353	-343				-10
	B	x	13	13				0
		y	-350	-336				-14
X12	A	x	80	84				-4
		y	-389	-400				11
	B	x	-74	-76				2
		y	-390	-394				4
XF	A	x	21	21	21	0	0	0
		y	-40	-35	-32	-8	-3	-5
	B	x	13	9	6	7	3	4
		y	-25	-20	-15	-10	-5	-5
XR	A	x	7	9	6	1	3	-2
		y	-29	-15	-6	-23	-9	-14
	B	x	43	36	35	8	1	7
		y	70	79	83	-13	-4	-9

Reference Beam

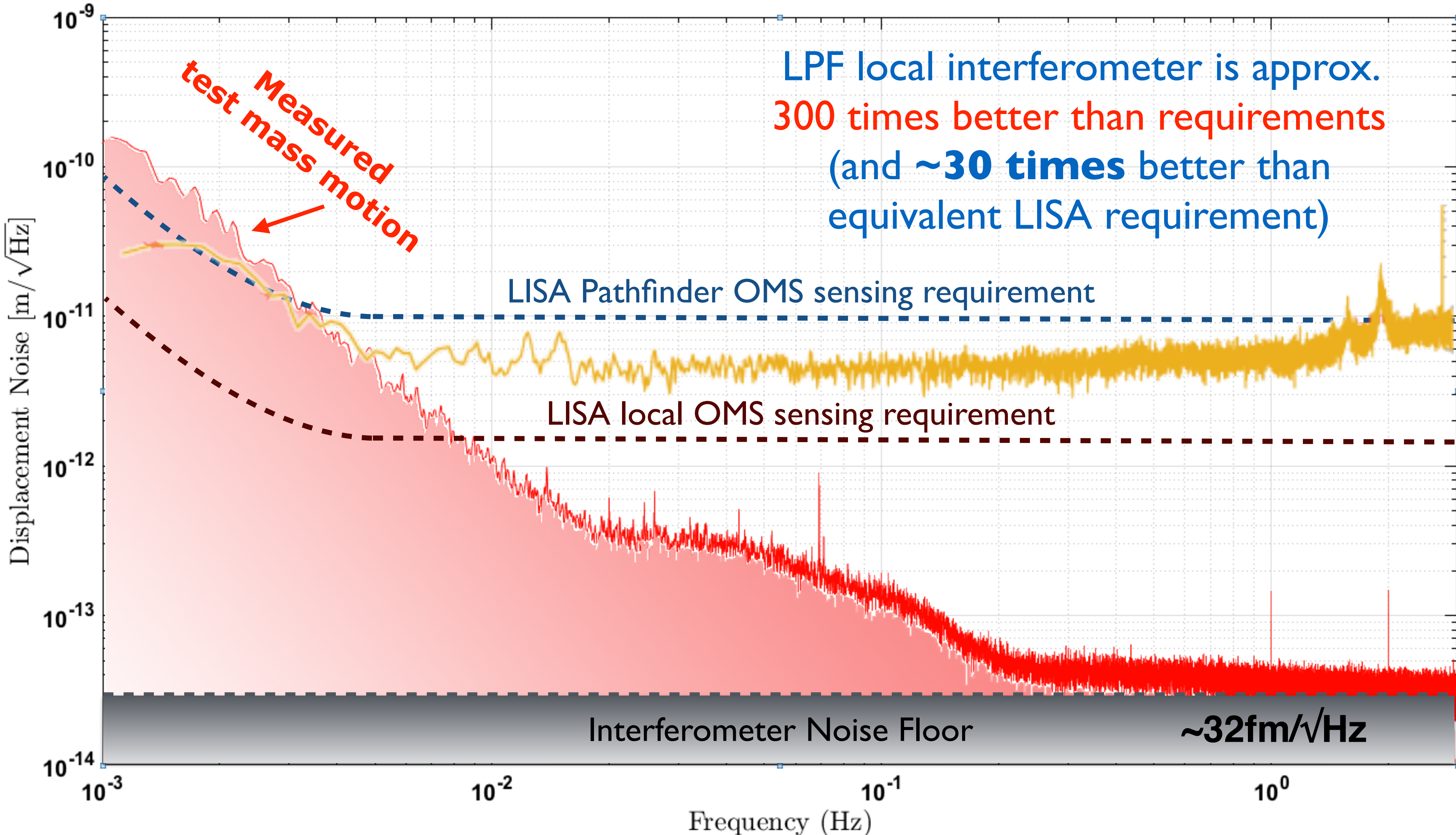
[um]			Flight	IABG	UGL	Flight - UGL	IABG - UGL	Flight - IABG
X1	A	x	12	18				-6
		y	-3	-7				4
	B	x	-5	-4				-1
		y	-9	-16				7
X12	A	x	18	13				5
		y	-23	-23				0
	B	x	8	11				-3
		y	16	16				0
XF	A	x	26	19	21	5	-2	7
		y	-35	-35	-29	-6	-6	0
	B	x	7	11	8	-1	3	-4
		y	-19	-20	-13	-6	-7	1
XR	A	x	-8	-11	-13	5	2	3
		y	-10	-12	-6	-4	-6	2
	B	x	60	59	58	2	1	1
		y	89	83	89	0	-6	6



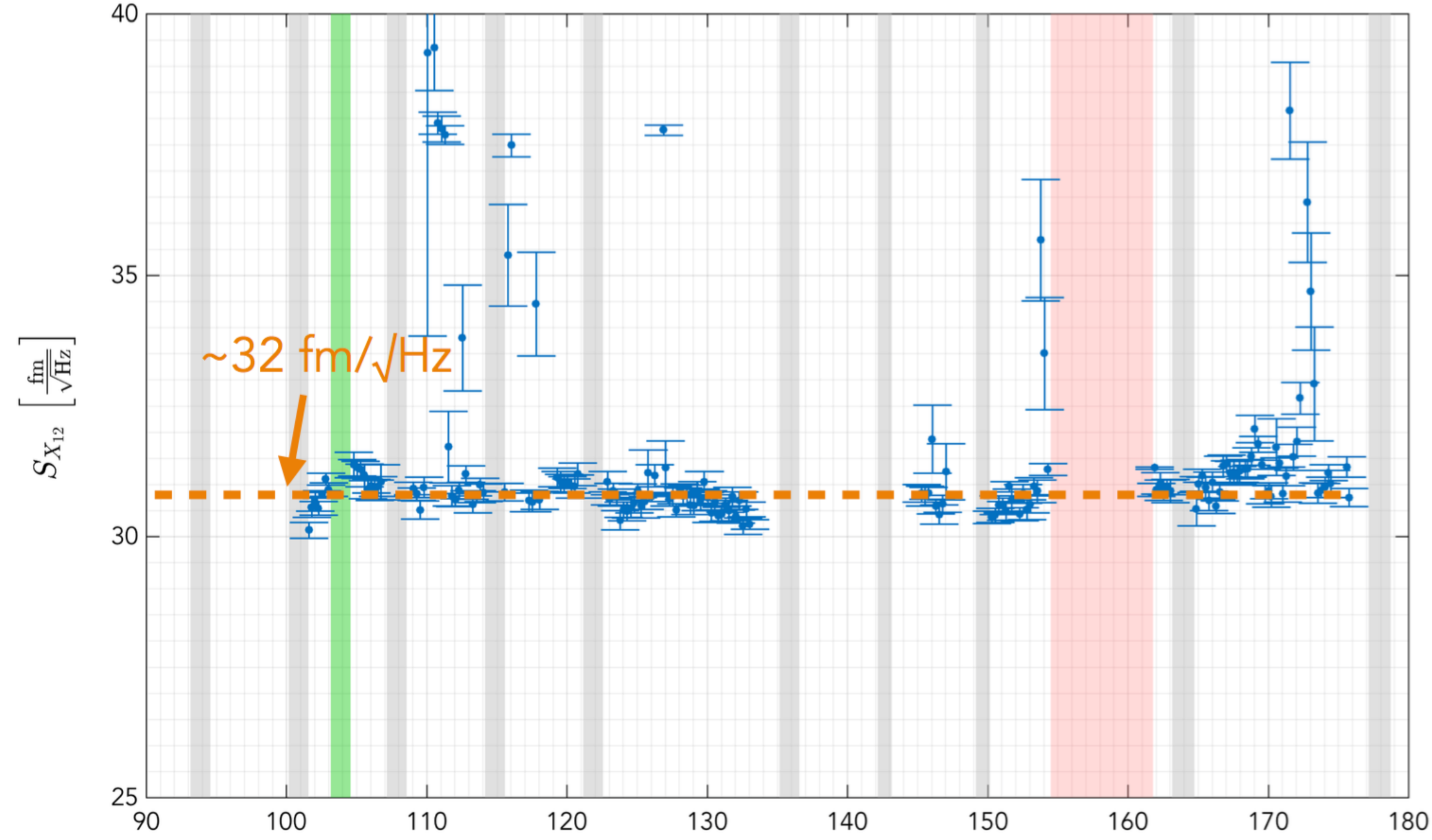
# Performance: On-Orbit results



# Performance: On-Orbit results



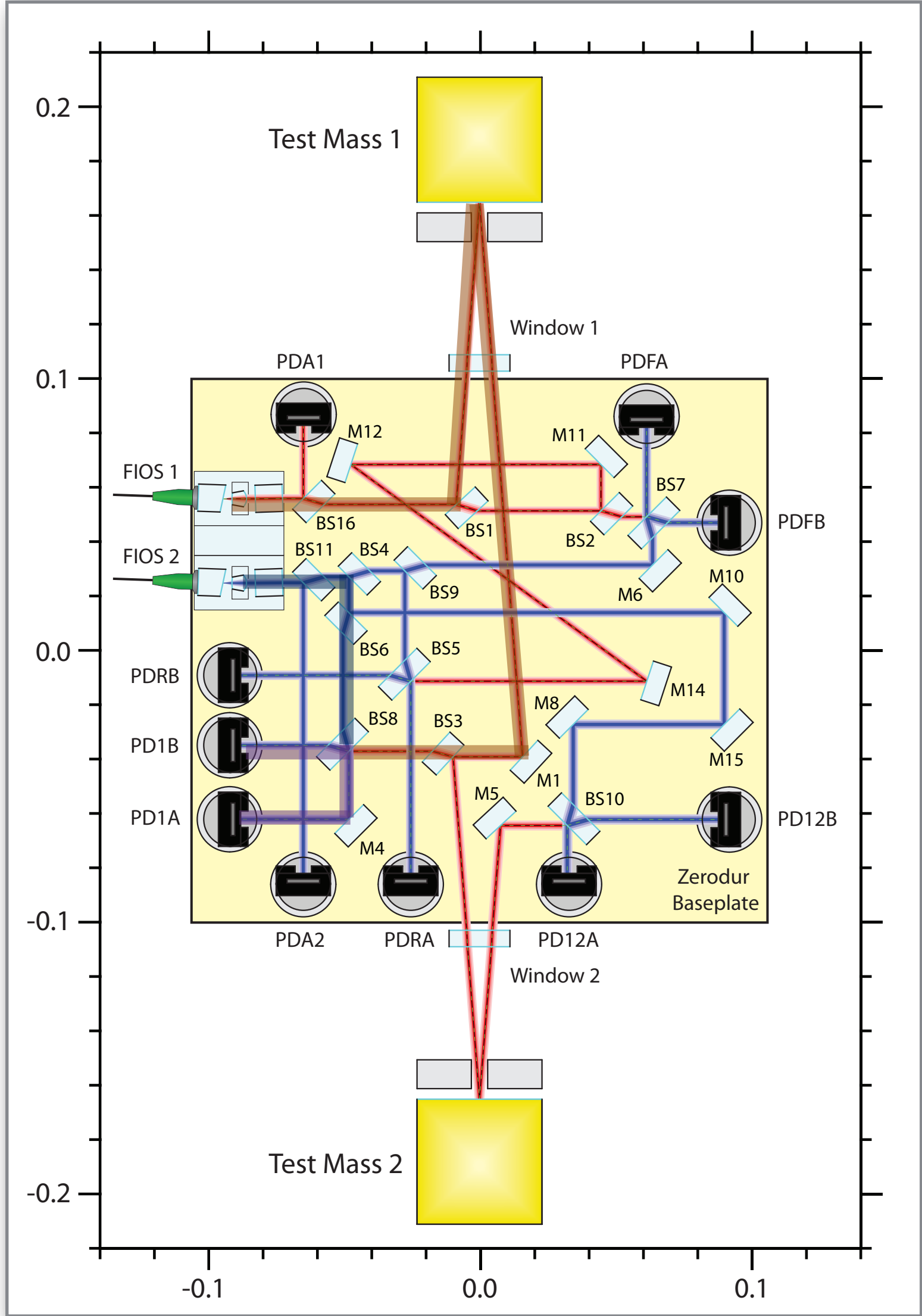
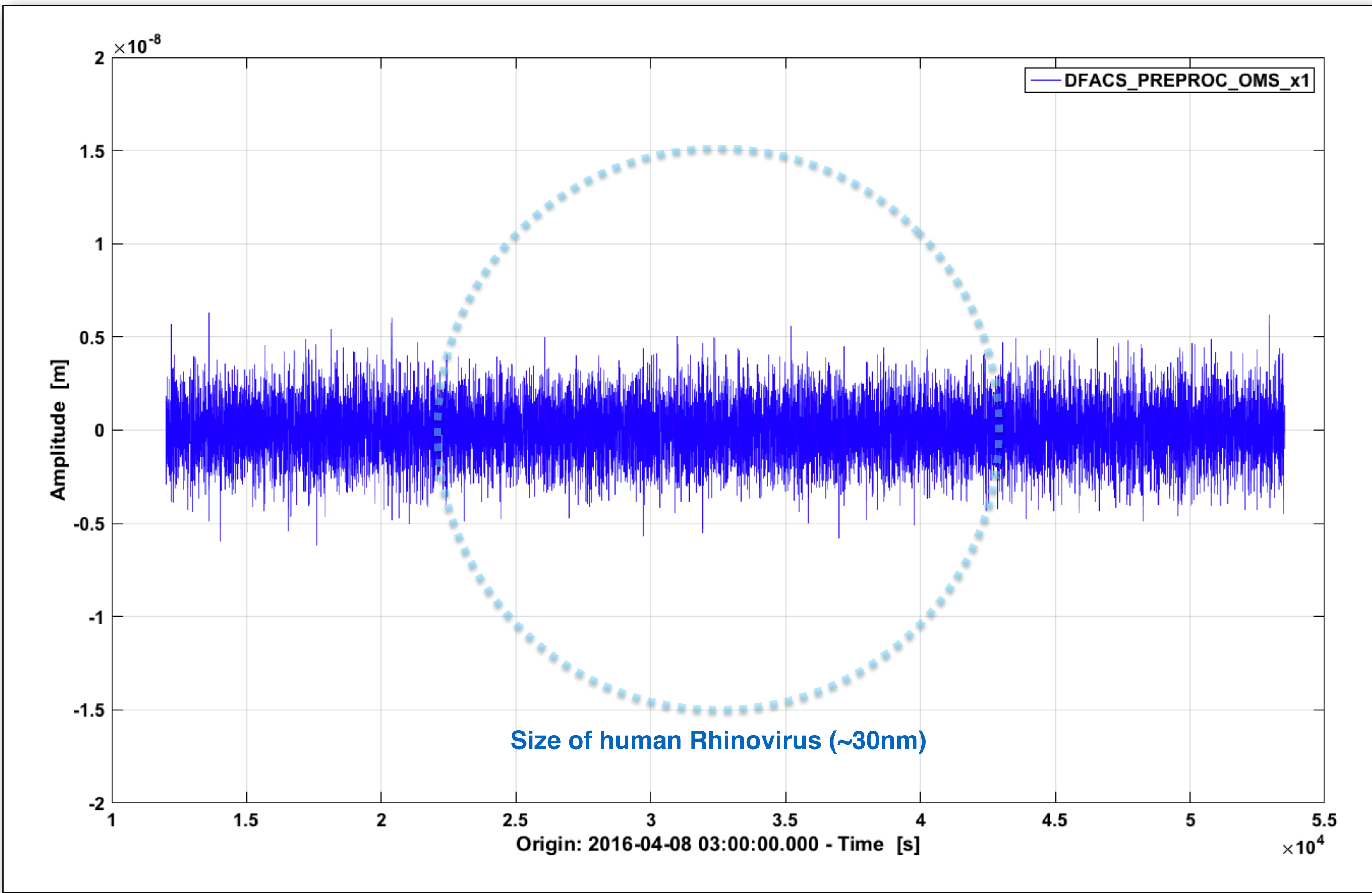
# Stability of performance



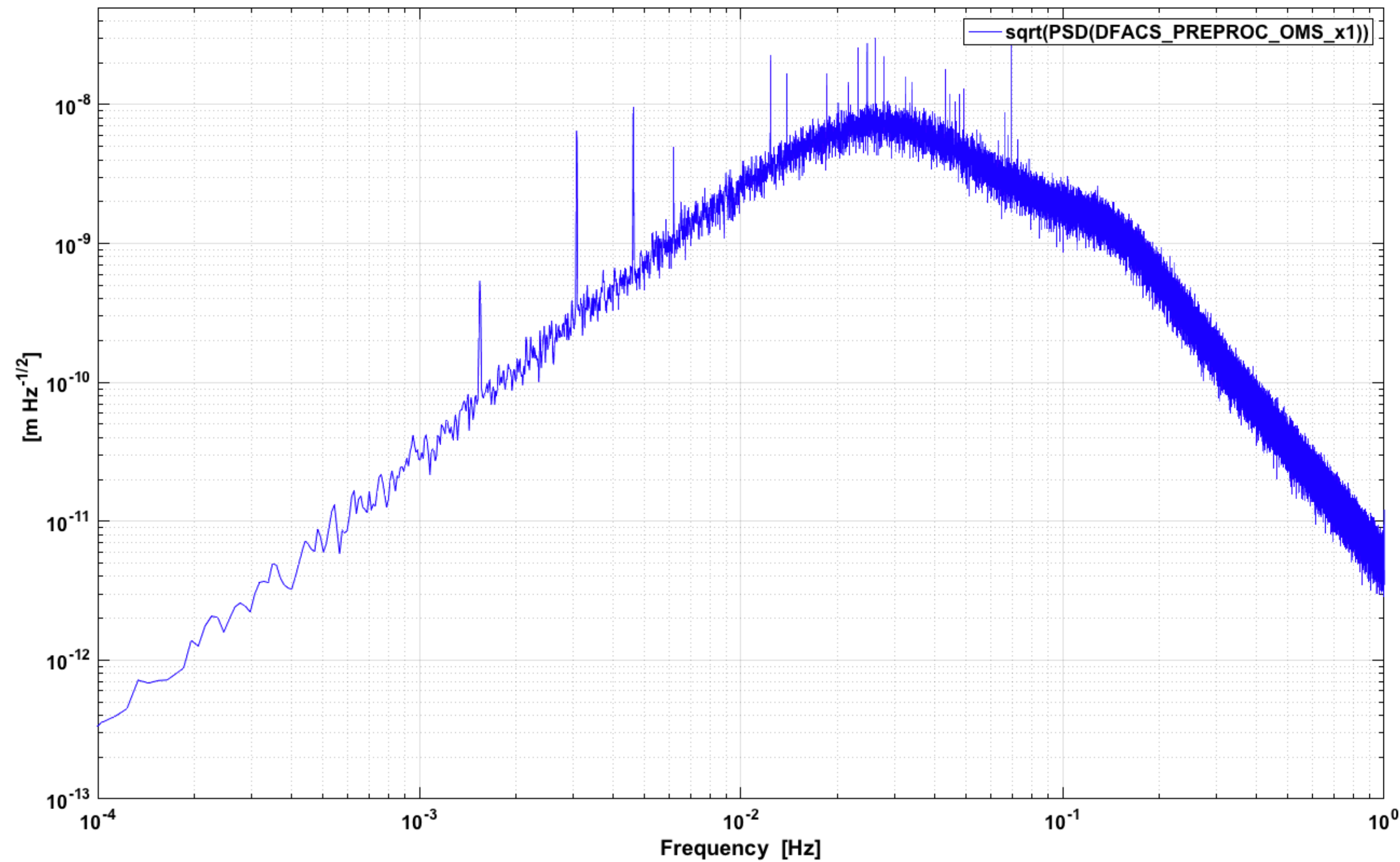
*each data point is 6 hours of science measurement* Time from launch (d)



# What about the satellite stability?



- By looking at the position of one test mass with respect to the optical bench (spacecraft), the only thing we measure is thruster noise!

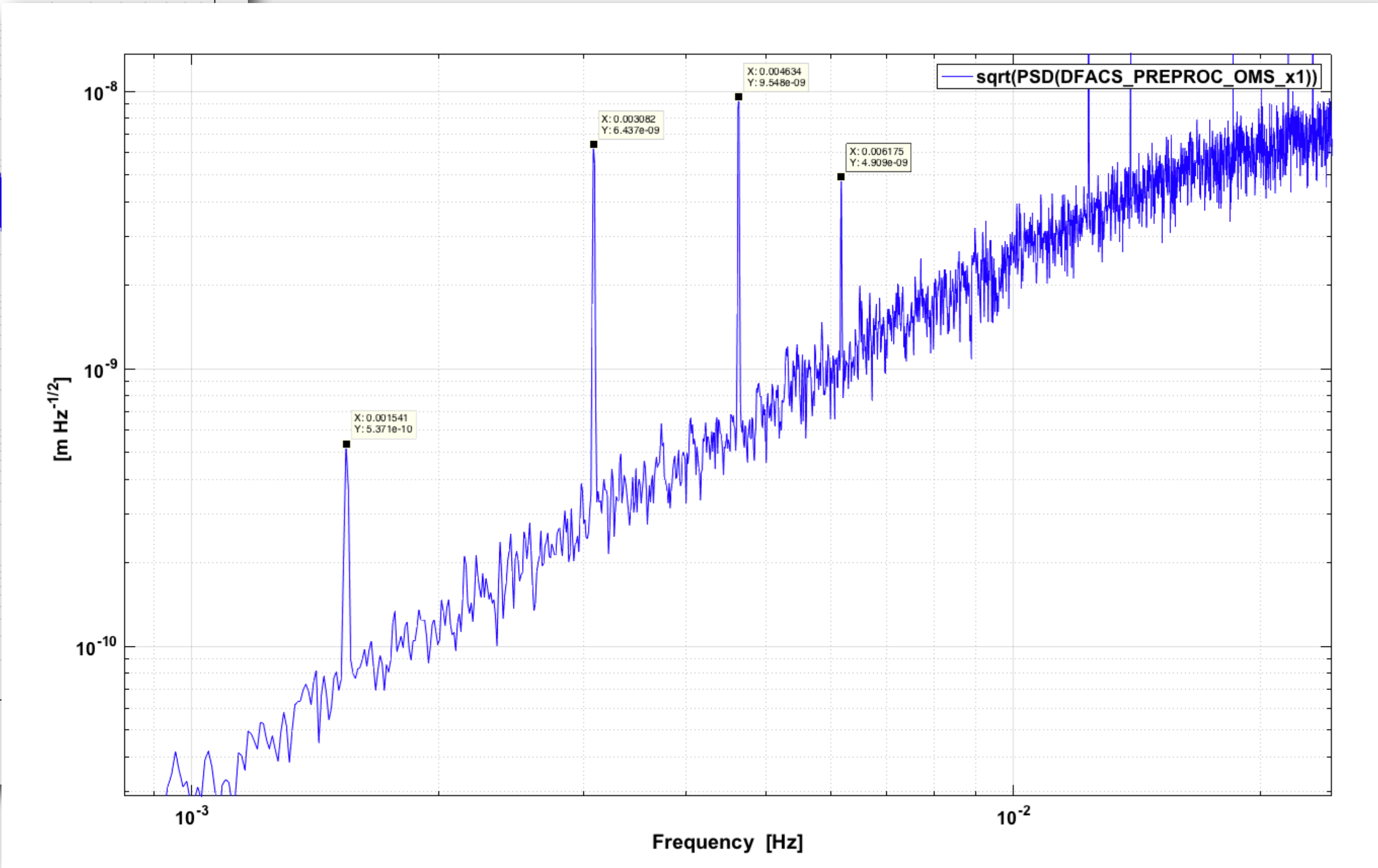
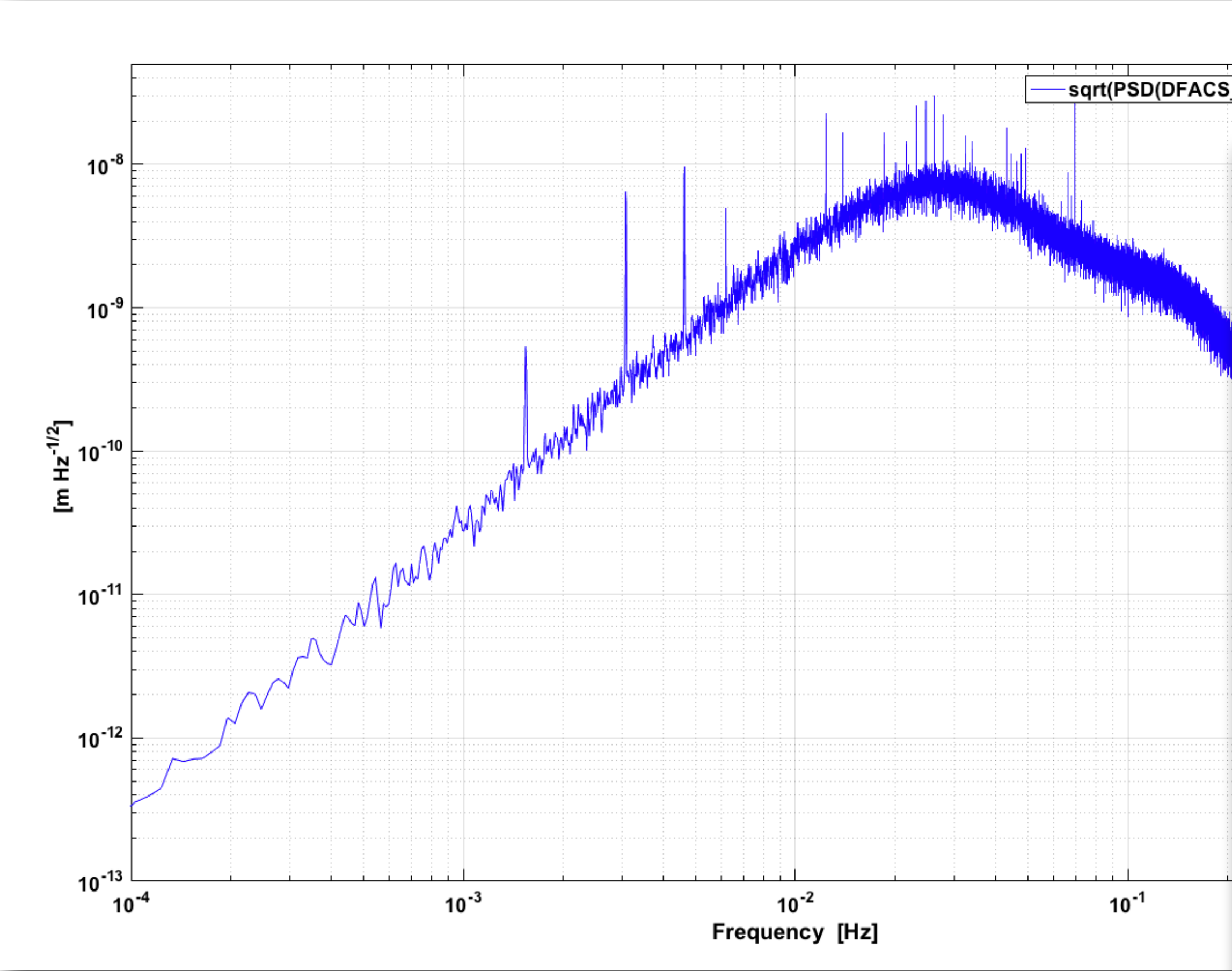




# Platform Stability



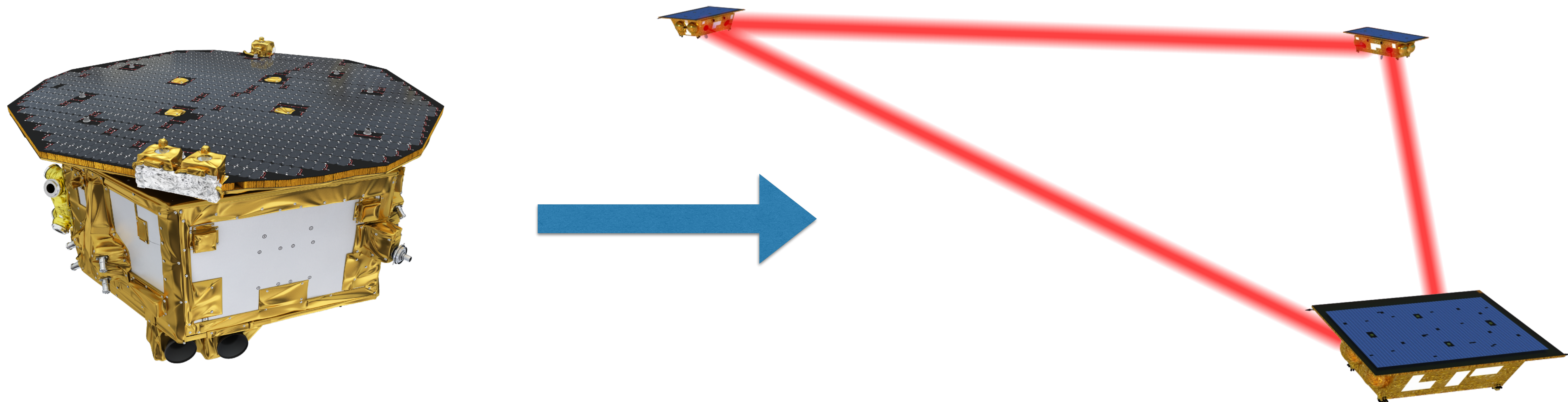
By looking at the position of one test mass with respect to the optical bench (spacecraft), the only thing we measure is thruster noise!



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- LISA Pathfinder has been a great success
  - Performance of both OMS and GRS have vastly exceeded requirements
- Success of LPF led to the early selection of LISA as the 3rd L-class mission in the Cosmic Vision Programme
  - LISA Mission Consolidation Review (mid Phase A review) was closed last week
- In addition, we have proven that fundamental physics missions are possible
- Lessons learned from LPF are being directly transferred to the LISA development



# Thank you



**ESA ESTEC**

**ESA ESAC**

**ESA ESOC**

**Airbus Defence and Space UK**

**Airbus Defence and Space D**

**University of Trento**

**Albert Einstein Institute**

**University of Glasgow**

**University of Birmingham**

**Imperial College London**

**ETH Zurich**

**University of Zurich**

**Institut d-Estudis Espacials de Catalunya**

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**BUSEK**

